CS738: Advanced Compiler Optimizations Interprocedural Data Flow Analysis

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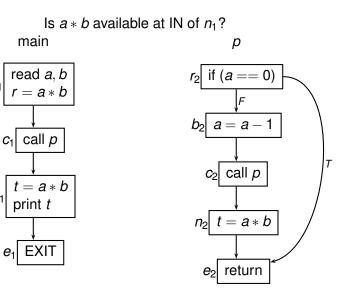


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Interprocedural Analysis: WHY?

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Infeasible paths



Infeasible paths

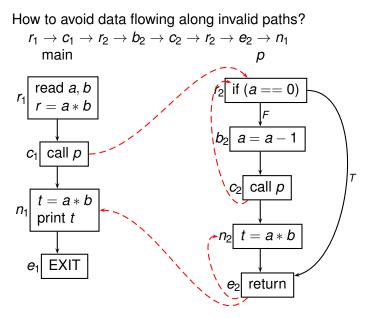
Recursion

- Infeasible paths
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- Function pointers and virtual functions

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- Function pointers and virtual functions
- Dynamic functions (functional programs)

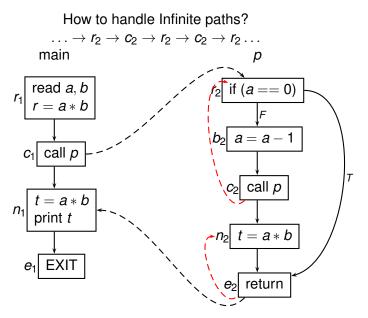
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Infeasible Paths



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Recursion



Target of a function can not be determined statically

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Function Pointers (including virtual functions)

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double (*fun) (double arg);
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if (cond)
   fun = sqrt;
else
   fun = fabs;
...
fun(x);
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- Dynamically created functions (in functional languages)
- No static control flow graph!

Functional approach

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procedures as structured blocks

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- input-output relation (*functions*) for each block

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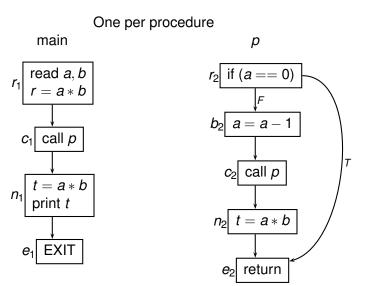
M. Sharir, and A. Pnueli. **Two Approaches to Inter-Procedural Data-Flow Analysis**. In Jones and Muchnik, editors, Program Flow Analysis: Theory and Applications. Prentice-Hall, 1981.

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Notations and Terminology

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Control Flow Graph



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Single instruction basic blocks



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- Unique exit block, denoted ep

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 - ▶ path_G(m, n): Set of all path in graph G = (N, E) leading from m to n

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Parameterless procedures, to ignore the problems of

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 - recursion stack for formal parameters

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 - aliasing
 - recursion stack for formal parameters
- No procedure variables (pointers, virtual functions etc.)

Data Flow Framework

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- *f*(*m*,*n*) ∈ *F* represents propagation function for edge (*m*, *n*) of control flow graph *G* = (*N*, *E*)

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- *f*(*m*,*n*) ∈ *F* represents propagation function for edge (*m*, *n*) of control flow graph *G* = (*N*, *E*)
 - Change of DF values from the start of m, through m, to the start of n

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Data Flow Equations

$$x_r = BoundaryInfo$$

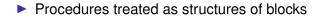
 $x_n = \bigwedge_{(m,n)\in E} f_{(m,n)}(x_m) \qquad n \in N-r$

MFP solution, approximation of MOP

$$y_n = \bigwedge \{ f_p(BoundaryInfo) : p \in \text{path}_G(r, n) \} \quad n \in N$$

Functional Approach to Interprocedural Analysis

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- Computes relationship between DF value at entry node and related data at *any* internal node of procedure

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 At call site, DF value propagated directly using the computed relation

First Representation:

$$G = \bigcup \{G_p : p \text{ is a procedure in program} \}$$

$$G_p = (N_p, E_p, r_p)$$

$$N_p$$
 = set of all basic block of p

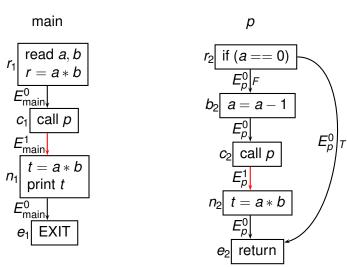
$$r_p$$
 = root block of p

$$E_p$$
 = set of edges of p

$$= E_p^0 \cup E_p^1$$

- $(m, n) \in E_p^0 \iff$ direct control transfer from m to n
- $(m, n) \in E_p^1 \iff m$ is a call block, and *n* immediately follows *m*

Interprocedural Flow Graph: 1st Representation



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Second representation

$$G^* = (N^*, E^*, r_1)$$

$$r_1 = \text{root block of main}$$

$$N^* = \bigcup_p N_p$$

$$E^* = E^0 \cup E^1$$

$$E^0 = \bigcup_p E^0_p$$

$$(m, n) \in E^1 \iff (m, n) \text{ is either a } call \text{ edge}$$
or a *return* edge

Call edge (m, n):



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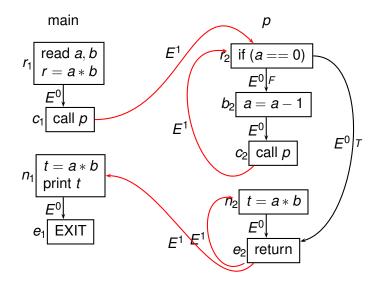
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- if p = q and
- $(m, n) \in E_s^1$ for some procedure *s*

Interprocedural Flow Graph: 2nd Representation





 \blacktriangleright G^{*} ignores the special nature of call and return edges



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- ▶ Path $q \in \text{path}_{G^*}(r_1, n)$ is in IVP (r_1, n)

• iff sequence of all E^1 edges in q (denoted q_1) is proper

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 - i > 1; and
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 - q'_1 obtained from deleting $q_1[i 1]$ and $q_1[i]$ from q_1 is proper

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Interprocedurally Valid Complete Paths

▶ $IVP_0(r_p, n)$ for procedure *p* and node $n \in N_p$

Interprocedurally Valid Complete Paths

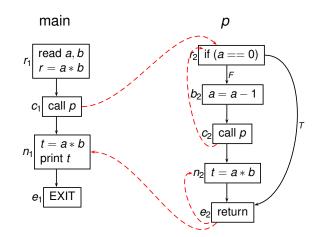
- ▶ $IVP_0(r_p, n)$ for procedure *p* and node $n \in N_p$
- set of all interprocedurally valid paths q in G* from r_p to n s.t.

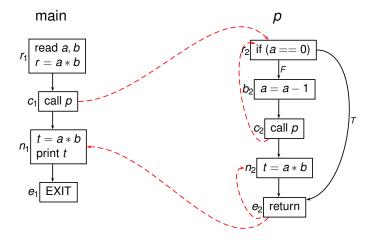
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Interprocedurally Valid Complete Paths

- ▶ $IVP_0(r_p, n)$ for procedure *p* and node $n \in N_p$
- set of all interprocedurally valid paths q in G* from r_p to n s.t.
 - Each call edge has corresponding return edge in q restricted to E¹

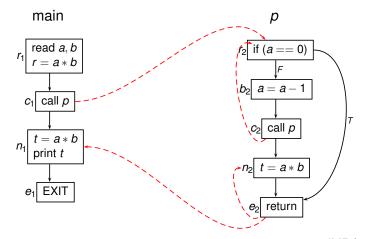
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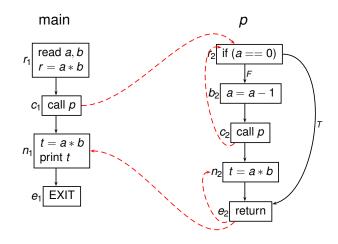
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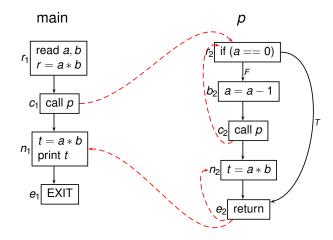
 $r_1 \rightarrow c_1 \rightarrow r_2 \rightarrow c_2 \rightarrow r_2 \rightarrow e_2 \rightarrow n_2 \rightarrow e_2 \rightarrow n_1 \rightarrow e_1 \in \mathsf{IVP}(r_1, e_1)$

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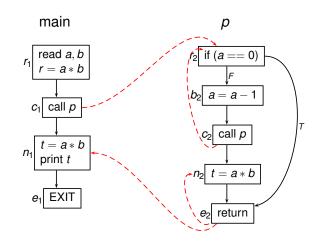


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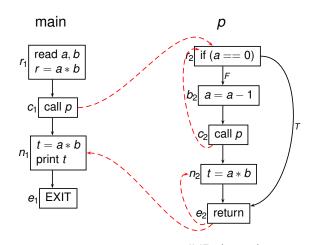


 $\textit{r}_1 \rightarrow \textit{c}_1 \rightarrow \textit{r}_2 \rightarrow \textit{c}_2 \rightarrow \textit{r}_2 \rightarrow \textit{e}_2 \rightarrow \textit{n}_1 \rightarrow \textit{e}_1 \not\in \mathsf{IVP}(\textit{r}_1,\textit{e}_1)$

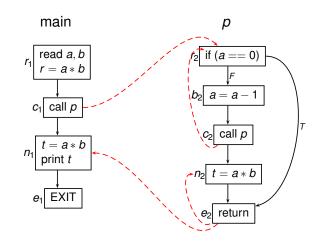


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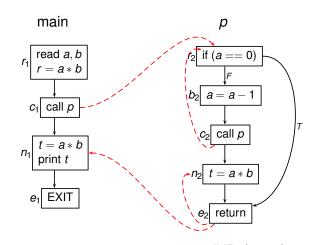


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Path Decomposition

- $q \in \mathsf{IVP}(r_{\mathsf{main}}, n)$
- $\begin{array}{lll} q & = & q_1 \parallel (c_1, r_{p_2}) \parallel q_2 \parallel \cdots \parallel (c_{j-1}, r_{p_j}) \parallel q_j \\ & & \text{where for each } i < j, q_i \in \mathsf{IVP}_0(r_{p_i}, c_i) \text{ and } q_j \in \mathsf{IVP}_0(r_{p_j}, n) \end{array}$