CS738: Advanced Compiler Optimizations Data Flow Analysis

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Agenda

Intraprocedural Data Flow Analysis: Classical Examples
 Last lecture: Reaching Definitions

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Agenda

Intraprocedural Data Flow Analysis: Classical Examples

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- Last lecture: Reaching Definitions
- Today: Available Expressions

Agenda

Intraprocedural Data Flow Analysis: Classical Examples

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- Last lecture: Reaching Definitions
- Today: Available Expressions
- Discussion about the similarities/differences

An expression e is available at a point p if

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An expression *e* is available at a point *p* if Every path from the *Entry* to *p* has at least one evaluation

Every path from the Entry to p has at least one evaluation of e

- An expression e is available at a point p if
 - Every path from the Entry to p has at least one evaluation of e

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There is no assignment to any component variable of e after the last evaluation of e prior to p

- An expression e is available at a point p if
 - Every path from the Entry to p has at least one evaluation of e

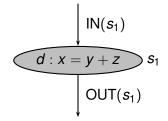
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- There is no assignment to any component variable of e after the last evaluation of e prior to p
- Expression e is generated by its evaluation

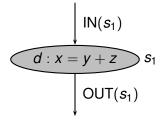
- An expression e is available at a point p if
 - Every path from the Entry to p has at least one evaluation of e

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- There is no assignment to any component variable of e after the last evaluation of e prior to p
- Expression e is generated by its evaluation
- Expression e is killed by assignment to its component variables



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 $OUT(s_1) = IN(s_1) - KILL(s_1) \cup GEN(s_1)$

$$\begin{array}{c}
 & | IN(s_1) \\
\hline
 & d: x = y + z \\
& 0UT(s_1)
\end{array}$$

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$$OUT(s_1) = IN(s_1) - KILL(s_1) \cup GEN(s_1)$$

 $GEN(s_1) =$

$$\begin{array}{c}
 & | IN(s_1) \\
\hline
 & d: x = y + z \\
& 0UT(s_1)
\end{array}$$

$$OUT(s_1) = IN(s_1) - KILL(s_1) \cup GEN(s_1)$$

$$GEN(s_1) = \{y + z\}$$

$$\begin{array}{c}
 & | IN(s_1) \\
\hline
 & d: x = y + z \\
& \downarrow OUT(s_1)
\end{array}$$

$$\begin{array}{c}
 & \downarrow \text{IN}(s_1) \\
\hline
 & d: x = y + z \\
 & \downarrow \text{OUT}(s_1)
\end{array}$$

$$OUT(s_1) = IN(s_1) - KILL(s_1) \cup GEN(s_1)$$

$$GEN(s_1) = \{y + z\}$$

$$KILL(s_1) = E_x$$

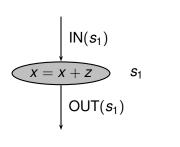
where $E : set of all expression having x as a component$

where E_x : set of all expression having x as a component

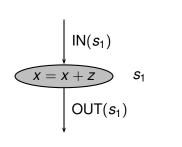
$$\begin{array}{c}
 & \downarrow \text{IN}(s_1) \\
\hline
 & d: x = y + z \\
 & \downarrow \text{OUT}(s_1)
\end{array}$$

This may not work in general – WHY?

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$$OUT(s_1) = IN(s_1) - KILL(s_1) \cup GEN(s_1)$$

$$\operatorname{GEN}(s_1) = \{x+z\}$$

$$KILL(s_1) = E_x$$

Incorrectly marks x + z as available after s_1

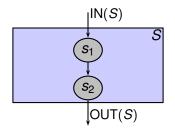
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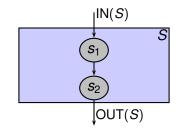
 $\operatorname{GEN}(s_1) = \emptyset$ for this case

$$|IN(s_1)|$$

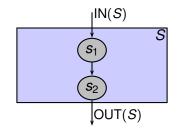
$$|Ihs = rhs \qquad s_1$$

$$|OUT(s_1)|$$



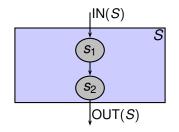


$$GEN(S) =$$

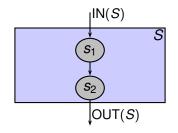


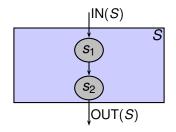
 $\operatorname{GEN}(S) = \operatorname{GEN}(s_1) - \operatorname{KILL}(s_2) \cup \operatorname{GEN}(s_2)$

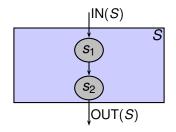
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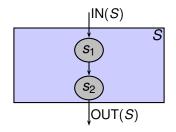


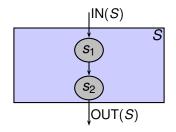
 $\begin{aligned} \mathsf{GEN}(S) &= & \mathsf{GEN}(s_1) - \mathsf{KILL}(s_2) \cup \mathsf{GEN}(s_2) \\ \mathsf{KILL}(S) &= & \end{aligned}$

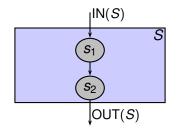


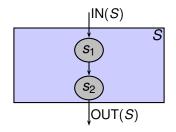


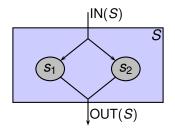


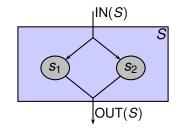






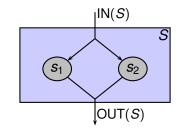






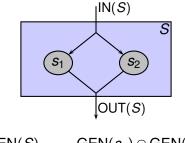
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GEN(S) =



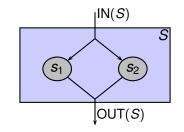
 $\operatorname{GEN}(S) = \operatorname{GEN}(s_1) \cap \operatorname{GEN}(s_2)$

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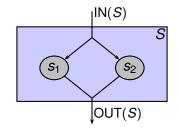


 $\begin{array}{lll} \mathsf{GEN}(S) &=& \mathsf{GEN}(s_1) \cap \mathsf{GEN}(s_2) \\ \mathsf{KILL}(S) &=& \end{array}$

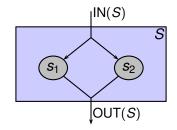
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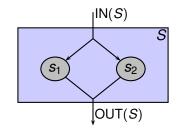


 $\begin{array}{lll} \mathsf{GEN}(S) &=& \mathsf{GEN}(s_1) \cap \mathsf{GEN}(s_2) \\ \mathsf{KILL}(S) &=& \mathsf{KILL}(s_1) \cup \mathsf{KILL}(s_2) \\ \mathsf{IN}(s_1) &=& \end{array}$

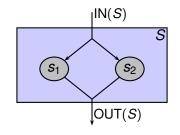


GEN(S)	=	$GEN(s_1)$	$\cap \mathbf{G}$	EN(<i>s</i> ₂)
KILL(S)	=	$KILL(s_1)$	∪KI	$LL(s_2)$
$IN(s_1)$	=	$IN(s_2)$	=	IN(S)

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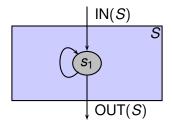


 $\operatorname{GEN}(S) = \operatorname{GEN}(s_1) \cap \operatorname{GEN}(s_2)$

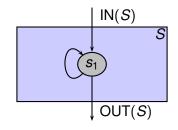
 $\mathsf{KILL}(S) = \mathsf{KILL}(s_1) \cup \mathsf{KILL}(s_2)$

 $IN(s_1) = IN(s_2) = IN(S)$

 $OUT(S) = OUT(s_1) \cap OUT(s_2)$

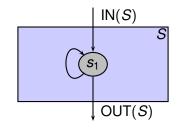


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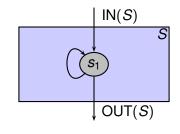
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$$GEN(S) =$$



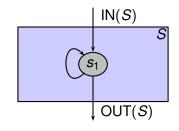
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 $\operatorname{GEN}(S) = \operatorname{GEN}(s_1)$



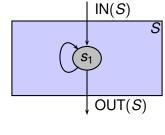
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 $\begin{array}{lll} \mathsf{GEN}(S) &=& \mathsf{GEN}(s_1)\\ \mathsf{KILL}(S) &=& \end{array}$



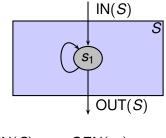
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$$\begin{array}{rcl} \mathsf{GEN}(S) &=& \mathsf{GEN}(s_1) \\ \mathsf{KILL}(S) &=& \mathsf{KILL}(s_1) \end{array}$$



$$GEN(S) = GEN(s_1)$$

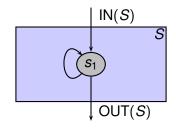
 $KILL(S) = KILL(s_1)$
 $OUT(S) =$



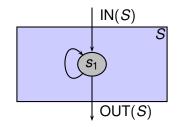
$$GEN(S) = GEN(s_1)$$

$$KILL(S) = KILL(s_1)$$

$$OUT(S) = OUT(s_1)$$



$$\begin{array}{rcl} \mathsf{GEN}(S) &=& \mathsf{GEN}(s_1)\\ \mathsf{KILL}(S) &=& \mathsf{KILL}(s_1)\\ \mathsf{OUT}(S) &=& \mathsf{OUT}(s_1)\\ \mathsf{IN}(s_1) &=& \end{array}$$



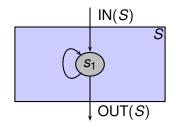
$$GEN(S) = GEN(s_1)$$

$$KILL(S) = KILL(s_1)$$

$$OUT(S) = OUT(s_1)$$

$$IN(s_1) = IN(S) \cap GEN(s_1)$$

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$$\operatorname{GEN}(S) = \operatorname{GEN}(s_1)$$

$$KILL(S) = KILL(s_1)$$

$$\operatorname{den}(\mathbf{O}) = \operatorname{den}(\mathbf{O})$$

 $OUT(S) = OUT(s_1)$

$$d = d = d = n(s_1)$$

$$(U \cup (C)) = U \cup (C)$$

$$EII(0) = GEII(0)$$

$$EIN(S) = GEIN(S_1)$$

$$\mathbb{E} \mathbb{I}(0) = \mathbb{E} \mathbb{I}(0)$$

$$IEN(3) = GEN(3_1)$$

$$\mathsf{I}(S) = \mathsf{GEN}(s_1)$$

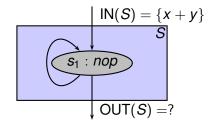
$$\mathsf{N}(S) = \mathsf{GEN}(s_1)$$

$$S) = GEN(s_1)$$

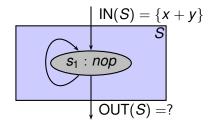
$$(S) = \operatorname{GEN}(s_1)$$

$$G = GEN(s_1)$$

 $IN(s_1) = IN(S) \cap GEN(s_1)$? $IN(s_1) = IN(S) \cap OUT(s_1)$?

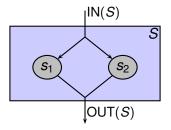


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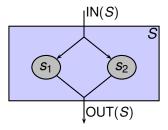
Is x + y available at OUT(S)?

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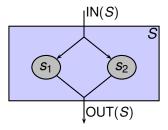
Assumption: All paths are feasible.



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- Assumption: All paths are feasible.
- Example:

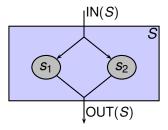
if (true) s1; else s2;



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- Assumption: All paths are feasible.
- Example:

if (true) s1; else s2;



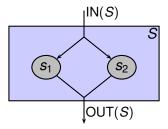
Assumption: All paths are feasible.

Example:

else s2;

FactComputedActualGEN(S)= $GEN(s_1) \cap GEN(s_2) \subseteq$ $GEN(s_1)$

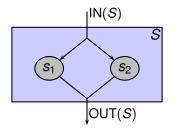
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Assumption: All paths are feasible.

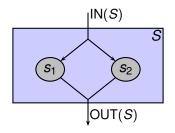
Example:

else s2;





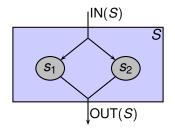




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► Thus,

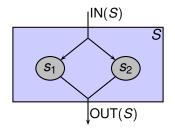
true $GEN(S) \supseteq$ analysis GEN(S)



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Thus,

true $GEN(S) \supseteq$ analysis GEN(S)true $KILL(S) \subseteq$ analysis KILL(S)

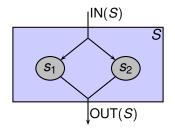


Thus,

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Fewer expressions marked available than actually do!

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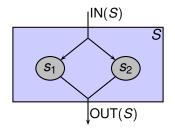
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Fewer expressions marked available than actually do!

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Later we shall see that this is SAFE approximation



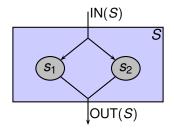
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Fewer expressions marked available than actually do!

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- Later we shall see that this is SAFE approximation
 - prevents optimizations



Thus,

true $GEN(S) \supseteq$ analysis GEN(S)true $KILL(S) \subseteq$ analysis KILL(S)

Fewer expressions marked available than actually do!

- Later we shall see that this is SAFE approximation
 - prevents optimizations
 - but NO wrong optimization

Expr e is available at the start of a block if

$$\mathsf{IN}(B) = \bigcap_{P \in \mathsf{PRED}(B)} \mathsf{OUT}(P)$$

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Expr *e* is available at the start of a block if
 It is available at the end of all predecessors
 IN(B) = ⋂ OUT(P)
 P∈PRED(B)

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Expr e is available at the start of a block if
 It is available at the end of all predecessors
 IN(B) = ∩ OUT(P)
 P∈PRED(B)

Expr e is available at the end of a block if

 $OUT(B) = IN(B) - KILL(B) \cup GEN(B)$

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Expr e is available at the start of a block if
 It is available at the end of all predecessors
 IN(B) = ∩ OUT(P)
 P∈PRED(B)

Expr e is available at the end of a block if

Either it is generated by the block

$$OUT(B) = IN(B) - KILL(B) \cup GEN(B)$$

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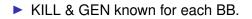
Expr *e* is available at the start of a block if
 It is available at the end of all predecessors
 IN(B) = ⋂ OUT(P)
 P∈PRED(B)

- Expr e is available at the end of a block if
 - Either it is generated by the block
 - Or it is available at the start of the block and not killed by the block

 $OUT(B) = IN(B) - KILL(B) \cup GEN(B)$

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Solving AvE Constraints





Solving AvE Constraints

- KILL & GEN known for each BB.
- A program with N BBs has 2N equations with 2N unknowns.

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Solving AvE Constraints

- KILL & GEN known for each BB.
- A program with N BBs has 2N equations with 2N unknowns.

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Solution is possible.

Solving AvE Constraints

- KILL & GEN known for each BB.
- A program with N BBs has 2N equations with 2N unknowns.

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- Solution is possible.
- Iterative approach (on the next slide).

for each block \boldsymbol{B} {

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for each block B { OUT(B) = U; U = "universal" set of all exprs

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for each block B {
 OUT(B) = U; U = "universal" set of all exprs
}
OUT(Entry) = ∅; // remember reaching defs?

```
for each block B {
    OUT(B) = U; U = "universal" set of all exprs
}
OUT(Entry) = 0; // remember reaching defs?
change = true;
while (change) {
    change = false;
```

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```
for each block B {
    OUT(B) = U; U = "universal" set of all exprs
}
OUT(Entry) = 0; // remember reaching defs?
change = true;
while (change) {
    change = false;
    for each block B other than Entry {
```

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```
for each block B {

OUT(B) = U; U = "universal" set of all exprs

}

OUT(Entry) = \emptyset; // remember reaching defs?

change = true;

while (change) {

    change = false;

    for each block B other than Entry {

    IN(B) = \bigcap_{P \in PRED(B)} OUT(P);
```

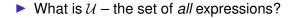
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```
for each block B {
	OUT(B) = U; U = "universal" set of all exprs
}
OUT(Entry) = \emptyset; // remember reaching defs?
change = true;
while (change) {
	change = false;
	for each block B other than Entry {
	IN(B) = \bigcap_{P \in PRED(B)} OUT(P);
	oldOut = OUT(B);
	OUT(B) = IN(B) - KILL(B) \cup GEN(B);
```

```
for each block B {
     OUT(B) = \mathcal{U}; \mathcal{U} = "universal" set of all exprs
}
OUT(Entry) = \emptyset; // remember reaching defs?
change = true;
while (change) {
     change = false;
     for each block B other than Entry {
          IN(B) = \bigcap_{P \in PRED(B)} OUT(P);
          oldOut = OUT(B);
          OUT(B) = IN(B) - KILL(B) \cup GEN(B);
          if (OUT(B) \neq oldOut) then {
              change = true;
```

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Some Issues

▶ What is *U* – the set of *all* expressions?

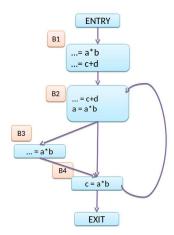
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How to compute it efficiently?

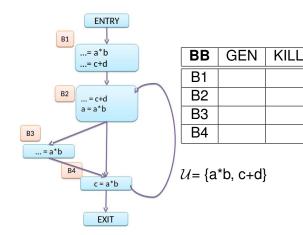
Some Issues

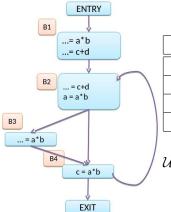
- ▶ What is *U* the set of *all* expressions?
- How to compute it efficiently?
- Why Entry block is initialized differently?

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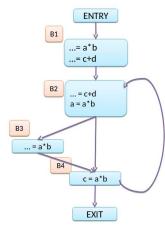




BB	GEN	KILL
B1	{a*b, c+d}	
B2		
B3		
B4		

$$\mathcal{U} = \{a^*b, c+d\}$$

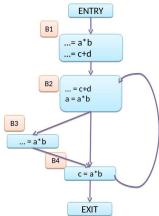
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B1	{a*b, c+d}	{ }
B2		
B3		
B4		

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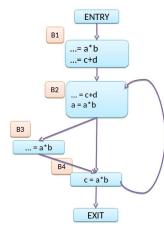
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BB	GEN	KILL
B1	{a*b, c+d}	{ }
B2	{c+d}	
B3		
B4		

 \mathcal{U} = {a*b, c+d}

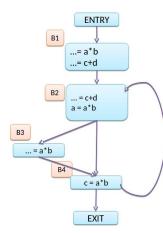
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BB	GEN	KILL
B1	{a*b, c+d}	{ }
B2	{c+d}	{a*b}
B3		
B4		

 \mathcal{U} = {a*b, c+d}

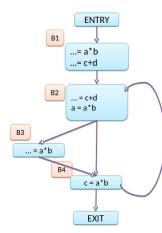
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BB	GEN	KILL
B1	{a*b, c+d}	{ }
B2	{c+d}	{a*b}
B3	{a*b}	
B4		

$$\mathcal{U} = \{a^*b, c+d\}$$

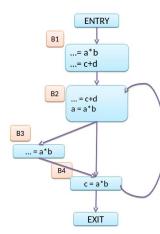
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BB	GEN	KILL
B1	{a*b, c+d}	{ }
B2	{c+d}	{a*b}
B3	{a*b}	{}
B4		

 \mathcal{U} = {a*b, c+d}

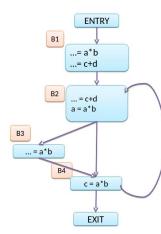
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BB	GEN	KILL
B1	{a*b, c+d}	{ }
B2	{c+d}	{a*b}
B3	{a*b}	{}
B4	{a*b}	

$$\mathcal{U} = \{a^*b, c+d\}$$

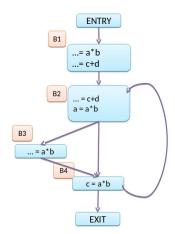
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BB	GEN	KILL
B1	{a*b, c+d}	{ }
B2	{c+d}	{a*b}
B3	{a*b}	{}
B4	{a*b}	{c+d}

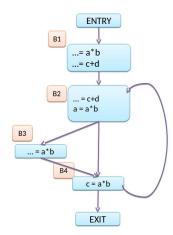
$$\mathcal{U} = \{a^*b, c+d\}$$

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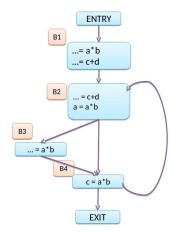
Pass#	Pt	B1	B2	B3	B4
Init	IN	-	-	-	-
	OUT	\mathcal{U}	U	U	U

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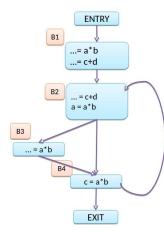
Pass#	Pt	B1	B2	B3	B4
Init	IN	-	-	-	-
	OUT	U	U	U	U
1	IN	Ø	a*b, c+d	c+d	c+d
			c+d		
	OUT	a*b, c+d	c+d	a*b, c+d	a*b
		c+d		c+d	

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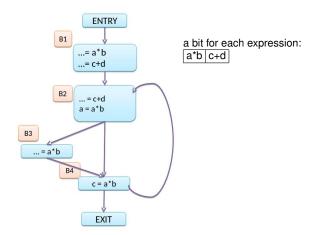
Pass#	Pt	B1	B2	B3	B4
Init	IN	-	-	-	-
	OUT	U	U	U	\mathcal{U}
1	IN	Ø	a*b,	c+d	c+d
			c+d		
	OUT	a*b, c+d	c+d	a*b,	a*b
		c+d		c+d	
2	IN	Ø	a*b	c+d	c+d
	OUT	a*b, c+d	c+d	a*b,	a*b
		c+d		c+d	

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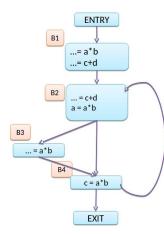


Pass#	Pt	B1	B2	B3	B4
Init	IN	-	-	-	-
	OUT	\mathcal{U}	U	U	U
1	IN	Ø	a*b,	c+d	c+d
			c+d		
	OUT	a*b,	c+d	a*b,	a*b
		c+d		c+d	
2	IN	Ø	a*b	c+d	c+d
	OUT	a*b,	c+d	a*b,	a*b
		c+d		c+d	
3	IN	Ø	a*b	c+d	c+d
	OUT	a*b,	c+d	a*b,	a*b
		c+d		c+d	

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a bit for each expression: a*b|c+d|

Pass#	Pt	B1	B2	B 3	B 4
Init	IN	-	-	-	-
	OUT	11	11	11	11
1	IN	00	11	01	01
	OUT	11	01	11	10
2	IN	00	10	01	01
	OUT	11	01	11	10
3	IN	00	10	01	01
	OUT	11	01	11	10

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Set-theoretic definitions:

$$\mathsf{IN}(B) = \bigcap_{P \in \mathsf{PRED}(B)} \mathsf{OUT}(P)$$

 $\mathsf{OUT}(B) = \mathsf{IN}(B) - \mathsf{KILL}(B) \cup \mathsf{GEN}(B)$

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Bitvector definitions:

$$\mathsf{IN}(B) = \bigwedge_{P \in \mathsf{PRED}(B)} \mathsf{OUT}(P)$$

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► Bitwise ∨, ∧, ¬ operators

Common subexpression elimination in a block B

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Common subexpression elimination in a block B
 Expression e available at the entry of B

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Common subexpression elimination in a block B

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- Expression e available at the entry of B
- e is also computed at a point p in B

Common subexpression elimination in a block B

- Expression e available at the entry of B
- e is also computed at a point p in B
- Components of e are not modified from entry of B to p

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Common subexpression elimination in a block B

- Expression e available at the entry of B
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e is "upward exposed" in B

Available Expressions: Application

Common subexpression elimination in a block B

- Expression e available at the entry of B
- e is also computed at a point p in B
- Components of e are not modified from entry of B to p

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- e is "upward exposed" in B
- Expressions generated in B are "downward exposed"



Some vs. All path property



Some vs. All path property

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• Meet operator: \cup vs. \cap

Some vs. All path property

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- Meet operator: \cup vs. \cap
- ▶ Initialization of *Entry*: Ø

- Some vs. All path property
- Meet operator: \cup vs. \cap
- ► Initialization of Entry: Ø
- Initialization of other BBs: Ø vs. U

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- Some vs. All path property
- Meet operator: \cup vs. \cap
- ► Initialization of Entry: Ø
- Initialization of other BBs: Ø vs. U
- Safety: "More" RD vs. "Fewer" AvE

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What if we Initialize:

 $OUT(B) = \emptyset, \forall B \text{ including } Entry$

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 $OUT(B) = \emptyset, \forall B \text{ including } Entry$

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Would we find "extra" available expressions?

What if we Initialize:

 $OUT(B) = \emptyset, \forall B \text{ including } Entry$

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Would we find "extra" available expressions?

More opportunity to optimize?

What if we Initialize:

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Would we find "extra" available expressions?

More opportunity to optimize?

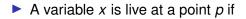
OR would we miss some expressions that are available?

What if we Initialize:

 $OUT(B) = \emptyset, \forall B \text{ including } Entry$

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- Would we find "extra" available expressions?
 - More opportunity to optimize?
- OR would we miss some expressions that are available?
 - Loose on opportunity to optimize?





A variable x is live at a point p if

There is a point p' along some path in the flow graph starting at p to the Exit

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There is a point p' along some path in the flow graph starting at p to the Exit

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Value of x could be used at p'

A variable x is live at a point p if

- There is a point p' along some path in the flow graph starting at p to the Exit
- Value of x could be used at p'
- There is no definition of x between p and p' along this path

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A variable x is live at a point p if

- There is a point p' along some path in the flow graph starting at p to the Exit
- Value of x could be used at p'
- There is no definition of x between p and p' along this path

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Otherwise x is dead at p

Live Variables: GEN

 GEN(B): Set of variables whose values may be used in block B prior to any definition

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- Also called "use(B)"
- "upward exposed use" of a variable in B

Live Variables: KILL

 KILL(B): Set of variables defined in block B prior to any use

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- Also called "def(B)"
- "upward exposed definition" of a variable in B

Live Variables: Equations

Set-theoretic definitions:

$$\mathsf{OUT}(B) = \bigcup_{S \in \mathsf{SUCC}(B)} \mathsf{IN}(S)$$

 $\mathsf{IN}(B) = \mathsf{OUT}(B) - \mathsf{KILL}(B) \cup \mathsf{GEN}(B)$

Live Variables: Equations

Set-theoretic definitions:

$$OUT(B) = \bigcup_{S \in SUCC(B)} IN(S)$$

 $IN(B) = OUT(B) - KILL(B) \cup GEN(B)$

Bitvector definitions:

$$\mathsf{OUT}(B) = \bigvee_{S \in \mathsf{SUCC}(B)} \mathsf{OUT}(S)$$

 $\mathsf{IN}(B) = \mathsf{OUT}(B) \land \neg \mathsf{KILL}(B) \lor \mathsf{GEN}(B)$

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Live Variables: Equations

Set-theoretic definitions:

$$\mathsf{OUT}(B) = \bigcup_{S \in \mathsf{SUCC}(B)} \mathsf{IN}(S)$$

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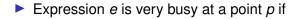
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► Bitwise ∨, ∧, ¬ operators





Expression e is very busy at a point p if

Every path from p to Exit has at least one evaluation of e

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- Expression e is very busy at a point p if
 - Every path from p to Exit has at least one evaluation of e
 - On every path, there is no assignment to any component variable of *e* before the first evaluation of *e* following *p*

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- Expression e is very busy at a point p if
 - Every path from p to Exit has at least one evaluation of e
 - On every path, there is no assignment to any component variable of *e* before the first evaluation of *e* following *p*

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Also called Anticipable expression

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Expression e is very busy at a point p if

Every path from p to Exit has at least one evaluation of e and there is no assignment to any component variable of e before the first evaluation of e following p on these paths.

- Set up the data flow equations for Very Busy Expressions (VBE). You have to give equations for GEN, KILL, IN, and OUT.
- Think of an optimization/transformation that uses VBE analysis. Briefly describe it (2-3 lines only)
- Will your optimization be safe if we replace "Every" by "Some" in the definition of VBE?