

# Information Theory Basics

(Lover, Thomas)

$\Omega$ : set of outcomes of a randomized experiment

(sample space)

$P: \mathcal{P}(\Omega) \rightarrow [0, 1]$  is called a probability distribution if

(1)  $P(\emptyset) = 0$

(2)  $\forall A \subseteq \Omega$

$$P(A) = 1 - P(A^c)$$

(3) If  $A_1, A_2, \dots$  are disjoint subsets of  $\Omega$ , then  $P\left(\bigcup_{i=1}^{\infty} A_i\right) = \sum P(A_i)$

If  $\Omega$  is discrete (i.e. finite or countably  $\infty$ ), then  $(\Omega, P)$  is called a

discrete probability space.

e.g. 1.  $\Omega = \{H, T\}$

$$P(\{H\}) = 0.5, \quad P(\{T\}) = 0.5$$

2.  $\Omega = \mathbb{N}$ .

$$\forall n \in \mathbb{N} \quad P(\{n\}) = \frac{1}{2^n}.$$

3.  $\Omega = \mathbb{N}$

$$\forall n \in \mathbb{N} \quad P(\{n\}) = \frac{6}{\pi^2} \frac{1}{n^2}, \quad \text{since} \quad \sum_{n=1}^{\infty} \frac{1}{n^2} = \frac{\pi^2}{6}$$

A random variable is a function  $X: \Omega \rightarrow \mathbb{R}$

Instead of talking about probabilities of events (i.e. subsets of  $\Omega$ ), we can define probability induced by a random variable.

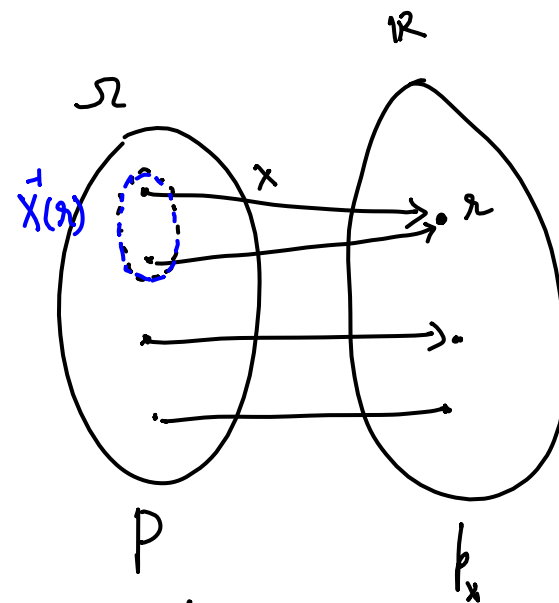
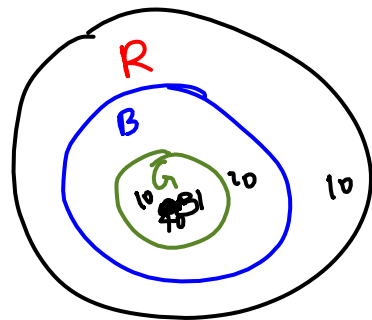
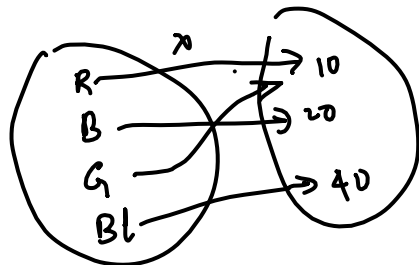
The probability distribution induced by  $X$  on  $\mathbb{R}$ , denoted  $p_x$  is defined for every  $x \in \mathbb{R}$  as

$$p_x(x) = P\left(\{\omega \in \Omega \mid X(\omega) = x\}\right) = P(X^{-1}(x))$$

Fig.

Game of darts with concentric rings with scores 10, 20, 10, 40 respectively for red, blue, green, black regions.

Let



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$$p_x(10) = P(\{\text{Red, Green}\}) = \frac{1}{2}.$$

$$p_x(20) = P(\{\text{Green}\}) = \frac{1}{4} \quad \& \quad p_x(40) = P(\{\text{Black}\}) = \frac{1}{4}$$

Let  $X: \Omega_1 \rightarrow \mathbb{R}$  and  $Y: \Omega_2 \rightarrow \mathbb{R}$  be 2 random variables. The joint

distribution

$p_{X,Y}: \Omega_1 \times \Omega_2 \rightarrow \mathbb{R}$  is defined as:

$$p_{X,Y}(x_1, x_2) = F\left(X^{-1}(x_1), Y^{-1}(x_2)\right)$$

where  $F$  is the joint distribution on  $\Omega_1 \times \Omega_2$ .

Example

$$\Omega_1, \Omega_2 = \{H, T\}$$

$$\Omega_1 \times \Omega_2 = \{(H, H), (H, T), (T, H), (T, T)\}$$

F is defined by the following table:

$\Omega_1 \backslash \Omega_2$	H	T	
H	0.3	0.4	0.7
T	0.1	0.2	0.3
	0.4	0.6	

← marginal  
 $= P_1(H)$

$= P_1(T)$

← Conditional  
 $P_{\Omega_2 | \Omega_1 = H} = \left( \frac{0.3}{0.7}, \frac{0.4}{0.7} \right)$   
 $P_{\Omega_2 | \Omega_1 = T} = \left( \frac{0.1}{0.3}, \frac{0.2}{0.3} \right)$

marginal  $P_2 \rightarrow P_2(H) \quad P_2(T)$   
 Conditional  $\rightarrow (0.3/0.4, 0.1/0.4) P_{\Omega_1 | \Omega_2 = H} \quad (0.4/0.6, 0.2/0.6)$

$P_{\Omega_1 | \Omega_2 = T}$