

Large-scale Multi-label Learning with Missing Labels

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Multi-label Learning

Setting:

- Data points: (\mathbf{x}, \mathbf{y}) , where $\mathbf{x} \in \mathbb{R}^d$, $\mathbf{y} \in \{0, 1\}^L$.
- $f(\mathbf{x}; Z)$ parameterized by Z :

$$f(\mathbf{x}; Z) = Z^T \mathbf{x}, Z \in \mathbb{R}^{d \times L}$$
- Applications: image/video annotation, query suggestions.

Existing Work

- Focus on Small L , label correlations
- Label-space reduction techniques
- Binary Relevance

Limits and challenges

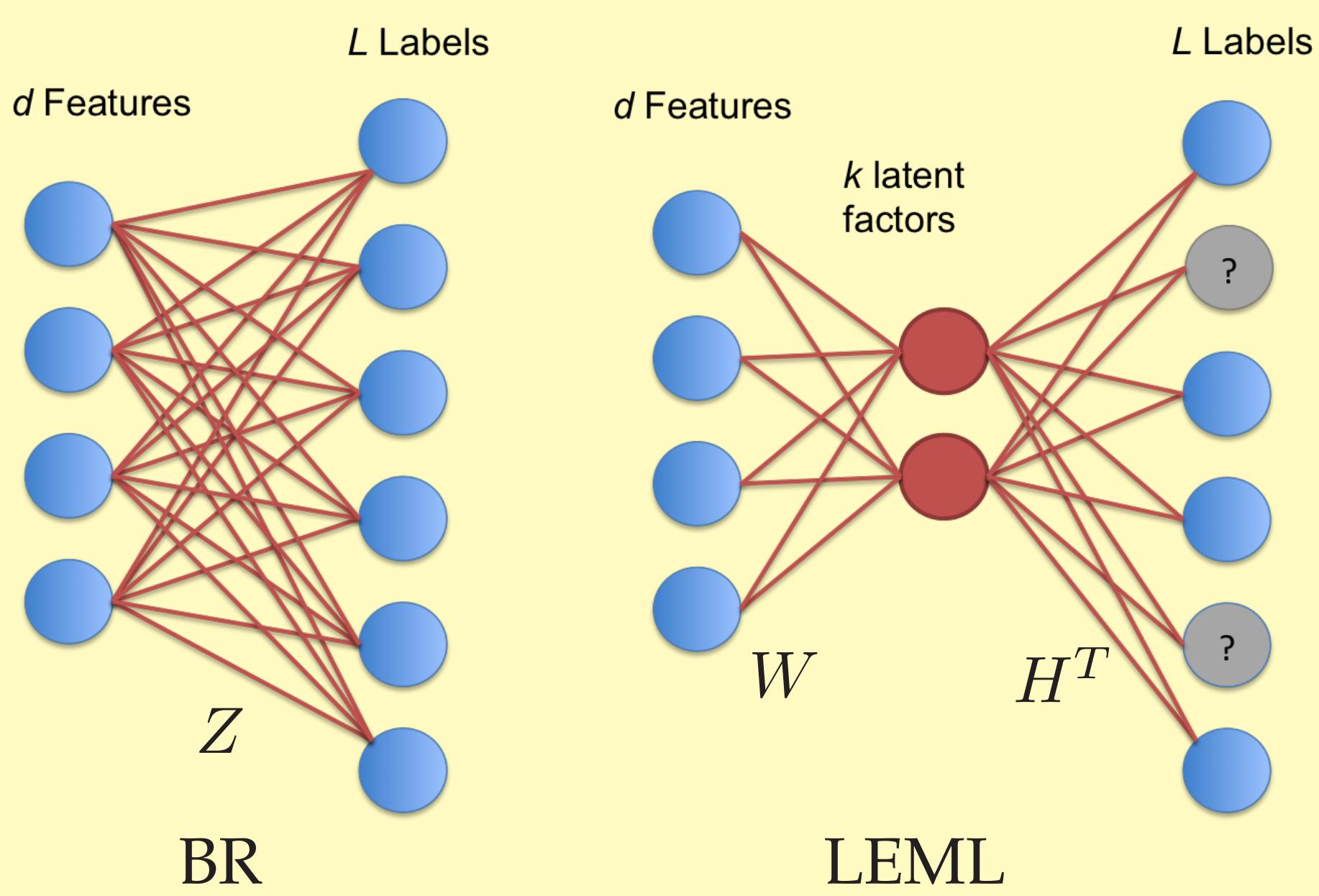
- Scaling to extreme large L : storage and computation costs
- Working in presence of missing labels

Our Proposed Solution: **LEML**

What is LEML

Low-rank ERM for Multi-Label Learning

- Learning model: $f(\mathbf{x}; Z) = Z^T \mathbf{x}$
- Low rank model: $Z = WH^T$
Latent factors \Leftarrow label correlations
Computational + space savings
- ERM framework:
Supports various loss functions
Handles missing labels



$$\hat{Z} = \arg \min_{Z \in \mathbb{R}^{d \times L}} J_\Omega(Z) \equiv \lambda \cdot r(Z) + \hat{\mathcal{L}}_\Omega(Z),$$

s.t. $\text{rank}(Z) \leq k$.

- Low-rank constrained regularization:

$$\text{rank}(Z) \leq k \text{ and } r(Z) = \|Z\|_{\text{tr}}$$

- Empirical risk on $\Omega = \{(i, j) : Y_{ij} \neq ?\}$:

$$\hat{\mathcal{L}}_\Omega(Z) = \sum_{(i,j) \in \Omega} \ell(Y_{ij}, f^j(\mathbf{x}_i; Z))$$

LEML: Motivation

Why Low-rank regularization?

- Significant **label correlations** when $L \gg 1$
 \Rightarrow required # of parameters should $\ll d \times L$
- Rank constrained regularization:
 \Rightarrow avoids overfitting
 \Rightarrow computational benefits
- Why Trace norm: \Rightarrow better at discovering latent structure.

Why Empirical risk minimization (ERM)?

- Unified approach for various loss functions
- Extension for the presence of missing labels
- Generalization error analysis
- Many existing label embedding approaches are just a *special case*

LEML generalizes CPLST

A special case of LEML:

- Squared- L_2 loss: $\ell(\mathbf{y}, f(\mathbf{x}; Z)) = \|\mathbf{y} - Z^T \mathbf{x}\|_2^2$
- No regularization: $\lambda = 0$
- Fully observed: $\Omega = [n] \times [L]$

$$\hat{Z} = V_X \Sigma_X^{-1} M_k = \arg \min_{Z: \text{rank}(Z) \leq k} J(Z) \equiv \|Y - XZ\|_F^2,$$

where $X = U_X \Sigma_X V_X^T$, M_k is the best rank- k approximation of $M \equiv U_X^T Y$.

CPLST (Chen and Lin, NIPS 2012):

- $f_C(\mathbf{x}; Z_C) = Z_C^T \mathbf{x}$
 - $Z_C = W_C H_C^T$, where W_C, H_C are minimizers of
- $$\min \|XW - YH\|_F^2 + \|Y - YHH^T\|_F^2,$$
- s.t. $H^T H = I_k$
- $Z_C = W_C H_C^T = V_X \Sigma_X^{-1} M_k = \hat{Z}$

In fully observed case,

CPLST \equiv LEML without regularization

Generalization Error Bounds

For general data distribution \mathcal{D} :

$$\mathcal{L}(\hat{Z}) \leq \inf_{\|Z\|_{\text{tr}} \leq \lambda} \mathcal{L}(Z) + \mathcal{O}\left(s\lambda\sqrt{\frac{1}{n}}\right) + \mathcal{O}\left(s\sqrt{\frac{\log \frac{1}{\delta}}{n}}\right)$$

For any near isotropic data distribution \mathcal{D} :

$$\mathcal{L}(\hat{Z}) \leq \inf_{\|Z\|_{\text{tr}} \leq \lambda} \mathcal{L}(Z) + \mathcal{O}\left(s\lambda\sqrt{\frac{1}{nL}}\right) + \mathcal{O}\left(s\sqrt{\frac{\log \frac{1}{\delta}}{n}}\right)$$

- Frobenius norm cannot achieve this.

LEML: MF with Side Features

In LEML, $\text{rank}(Z) \leq k$ and $r(Z) = \|Z\|_{\text{tr}}$

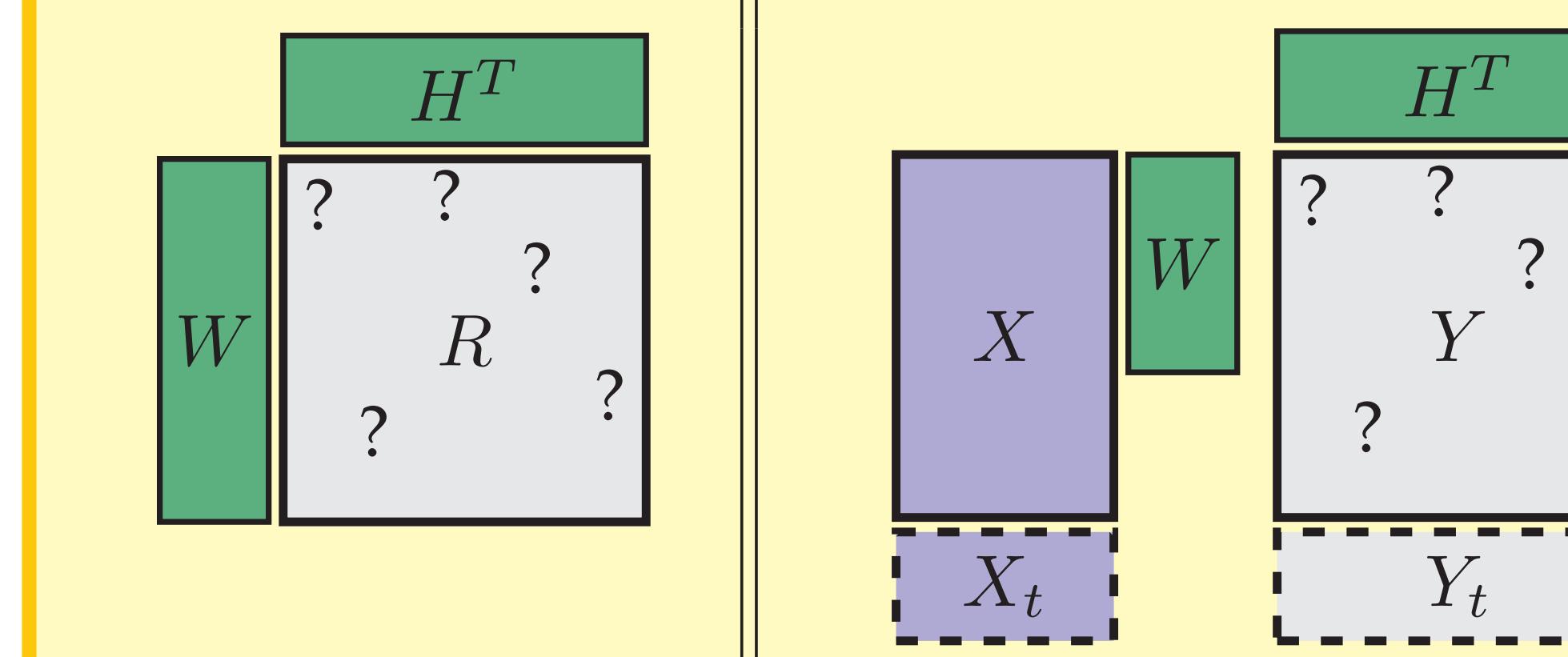
- $Z = WH^T$, where $W \in \mathbb{R}^{d \times k}$ and $H \in \mathbb{R}^{L \times k}$
- $r(Z) = \|Z\|_{\text{tr}} = \min_{W, H} \frac{1}{2} (\|W\|_F^2 + \|H\|_F^2)$
- $f^j(\mathbf{x}_i; Z) = \mathbf{x}_i^T W h_j$

Reformulation: $J_\Omega(Z) = J_\Omega(W, H) \equiv$

$$\sum_{(i,j) \in \Omega} \ell(Y_{ij}, \mathbf{x}_i^T W h_j) + \frac{\lambda}{2} (\|W\|_F^2 + \|H\|_F^2)$$

Matrix Factorization

$$R_{ij} \approx \mathbf{w}_i^T \mathbf{h}_j$$



Alternating minimization:

- For $t = 1, \dots$
 - $H^{(t)} \leftarrow \arg \min_H J_\Omega(W^{(t-1)}, H)$... easy
 - $W^{(t)} \leftarrow \arg \min_W J_\Omega(W, H^{(t)})$... hard

Efficient Updates

$$W^{(t)} \leftarrow \arg \min_W J_\Omega(W, H^{(t)})$$

- Rows of W are not independent.
- Closed form solution: $\mathcal{O}(n\bar{L}\bar{d}k^2 + d^3k^3)$ time, where $\bar{L} = |\Omega|/n$, $\bar{d} = \text{nnz}(X)/n$

Iterative solvers (e.g., conjugate gradient):

- gradient and Hessian-vector multiplication
- direct computation: $\mathcal{O}(n\bar{L}\bar{d}k)$ per operation

By exploiting the problem structure, we can

- reduce $\mathcal{O}(n\bar{L}\bar{d}k) \rightarrow \mathcal{O}(n\bar{L}k + ndk)$ for a general smooth loss, and
- reduce $\mathcal{O}(nLk) \rightarrow \mathcal{O}(\text{nnz}(Y)k)$ for squared- L_2 with full labels
- See paper for the detailed algorithms
- Key techniques:

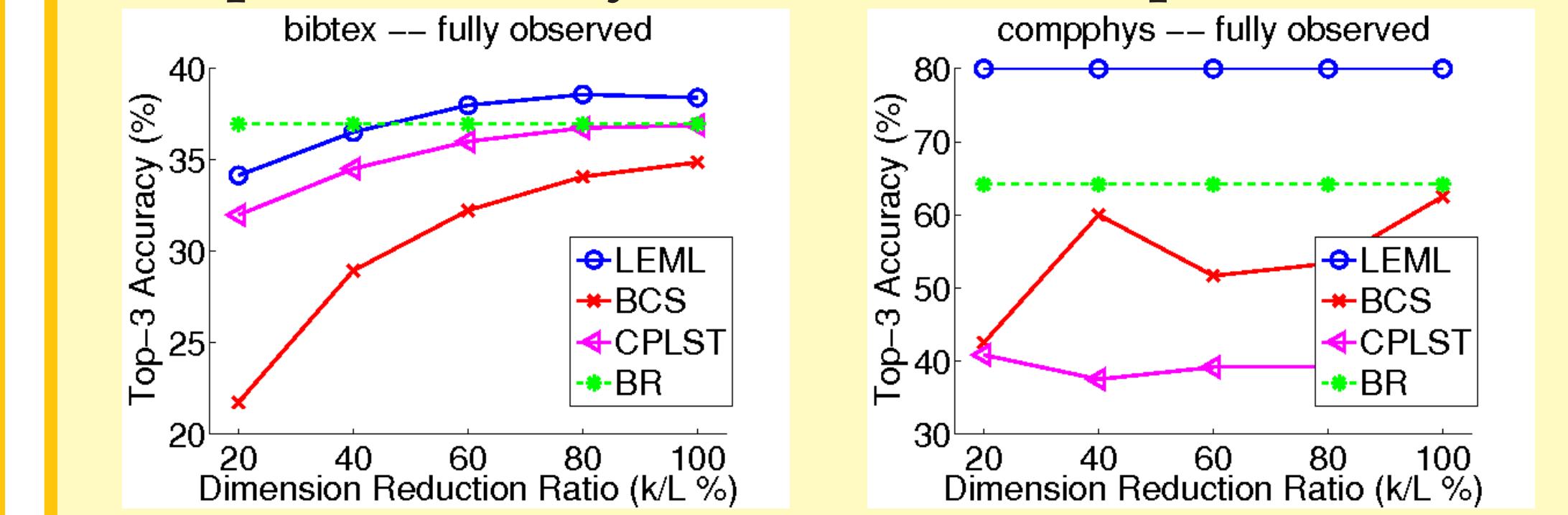
$$\sum_{(i,j) \in \Omega} C_{ij} \mathbf{a}_i \mathbf{b}_j^T = \underbrace{\mathbf{A}^T \mathbf{C} \mathbf{B}}_{\mathcal{O}(|\Omega|k+ndk)} \\ (B \otimes A) \text{vec}(D) = \underbrace{\text{vec}(ADB^T)}_{\mathcal{O}(ndk+nLk)}$$

Experimental Results

Datasets:

Dataset	Feature dimension d	Label dimension L	training n	test n
bibtex	1,836	68.74	159	2,400
autofood	9,382	143.92	162	155
compphys	33,284	792.78	208	9,800
eurlex	5,000	236.69	3,993	5,300
nus-wide	1,134	862.70	1,000	5,780
wiki	366,932	146.78	213,707	7,060
			4,880	2,515
			17,413	1,935
			161,789	107,859
			881,805	10,000

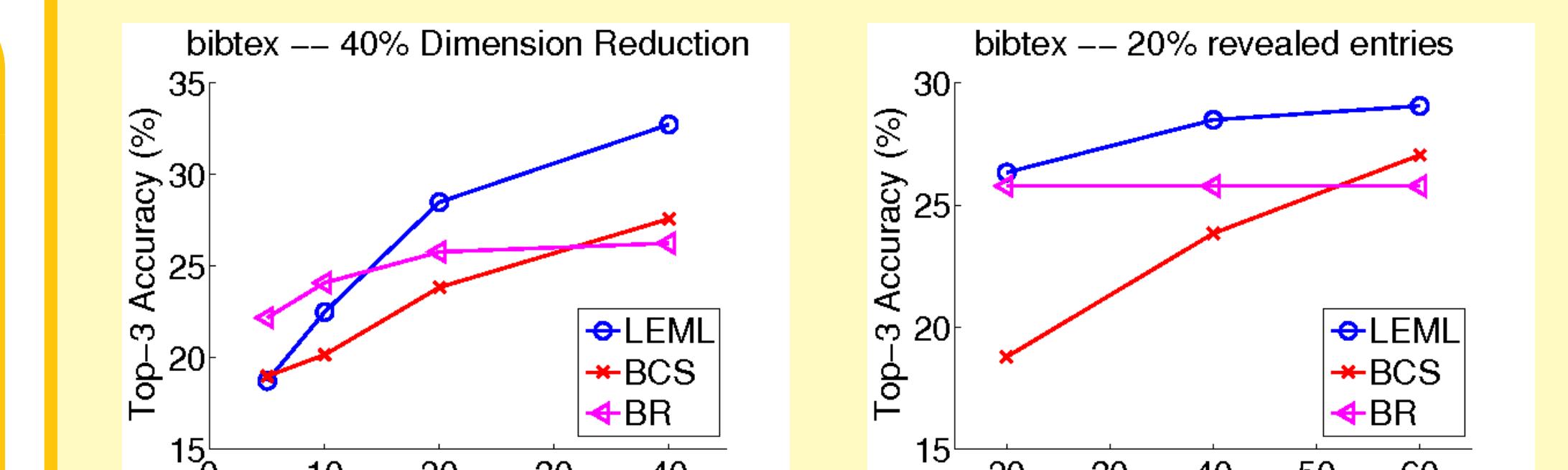
Comparison: Fully observation + Squared- L_2 loss



dataset	k	time (s)	WSABIE		
			top-1	top-3	
eurlex	250	175	51.99	39.79	0.9425
	500	487	56.90	44.20	0.9456
nus-wide	50	574	20.71	15.96	0.7741
	100	1,097	20.76	16.00	0.7718
wiki	250	9,932	19.56	14.43	0.9086
	500	18,072	22.83	17.30	0.9374

- CPLST suffers due to overfitting
- LEML can even beat BR for $k = L$ due to a trace norm regularizer.
- For wiki, MLR took 6 hours to get 0.9374, while WSABIE took 2 days to get 0.9058.

Comparison: Missing Labels + Squared- L_2 Loss



dataset	Top-3 Precision			Average AUC	
	Squared- L_2	Logistic	BR	LEML	BR
bibtex	28.50	23.84	25.78	25.79	31.92
autofood	67.54	35.09	62.28	71.05	53.51
compphys	65.00	35.83	31.67	60.00	28.33

dataset	Top-3		