

# Bayesian Inference for Gaussians, Working With Gaussians

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Topics in Probabilistic Modeling and Inference (CS698X)

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# Recap: Bayesian Inference for Mean of a Gaussian

- Consider  $N$  i.i.d. observations  $\mathbf{X} = \{x_1, \dots, x_N\}$  drawn from a one-dim Gaussian  $\mathcal{N}(x|\mu, \sigma^2)$

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- Exercise:** Compute the posterior if  $p(\mu) = \mathcal{N}(\mu|\mu_0, \frac{\sigma^2}{\kappa_0})$ . Also, what does  $\kappa_0$  mean intuitively?



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- The posterior is also gamma:  $p(\lambda|\mathbf{X}) = \text{Gamma}\left(\alpha + \frac{N}{2}, \beta + \frac{\sum_{n=1}^N (x_n - \mu)^2}{2}\right)$

- Exercise: Work out (or look up) the posterior predictive  $p(x_*|\mathbf{X})$  in these cases (isn't Gaussian)



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- The above is known as the **Normal-gamma** (NG) distribution (product of a Normal and a gamma)

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# An Aside: generalized-t and Student-t distribution

- Obtained if we integrate out the precision of a Gaussian using a conjugate gamma prior

$$\begin{aligned} p(x|\mu, a, b) &= \int \mathcal{N}(x|\mu, \lambda^{-1}) \text{Gamma}(\lambda|a, b) d\lambda \\ &= t_{2a}(x|\mu, b/a) = t_\nu(x|\mu, \sigma^2) \quad (\text{generalized-t distribution}) \end{aligned}$$



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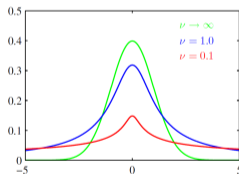


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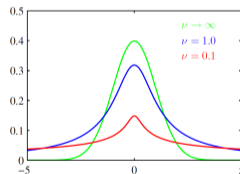


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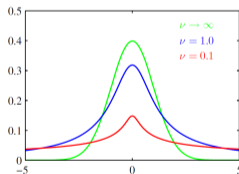


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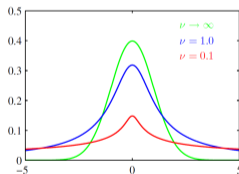


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- For further details (e.g., full equations, posterior predictive, etc), refer to “Conjugate Bayesian analysis of the Gaussian distribution” by Murphy (2007), or MLAPP Chapter 4



# Some Useful Properties of Gaussians



# Multivariate Gaussian: Some Alternative Representations

- The (multivariate) Gaussian with mean  $\boldsymbol{\mu}$  and cov. matrix  $\boldsymbol{\Sigma}$

$$\mathcal{N}(\mathbf{x}|\boldsymbol{\mu}, \boldsymbol{\Sigma}) = \frac{1}{\sqrt{(2\pi)^D |\boldsymbol{\Sigma}|}} \exp \left\{ -\frac{1}{2} (\mathbf{x} - \boldsymbol{\mu})^\top \boldsymbol{\Sigma}^{-1} (\mathbf{x} - \boldsymbol{\mu}) \right\}$$





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where  $\boldsymbol{\Lambda} = \boldsymbol{\Sigma}^{-1}$  and  $\boldsymbol{\xi} = \boldsymbol{\Sigma}^{-1} \boldsymbol{\mu}$  are the “natural parameters” (more when we discuss exp. family).



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$$\begin{aligned}\mathcal{N}(\mathbf{x}|\boldsymbol{\mu}, \boldsymbol{\Sigma}) &= \frac{1}{\sqrt{(2\pi)^D |\boldsymbol{\Sigma}|}} \exp \left\{ -\frac{1}{2} (\mathbf{x} - \boldsymbol{\mu})^\top \boldsymbol{\Sigma}^{-1} (\mathbf{x} - \boldsymbol{\mu}) \right\} \\ &= \frac{1}{\sqrt{(2\pi)^D |\boldsymbol{\Sigma}|}} \exp \left\{ -\frac{1}{2} \text{trace} \left[ \boldsymbol{\Sigma}^{-1} \mathbf{S} \right] \right\} \quad \text{where } \mathbf{S} = (\mathbf{x} - \boldsymbol{\mu})(\mathbf{x} - \boldsymbol{\mu})^\top\end{aligned}$$

- An alternate representation: The “information form”

$$\mathcal{N}_c(\mathbf{x}|\boldsymbol{\xi}, \boldsymbol{\Lambda}) = (2\pi)^{-D/2} |\boldsymbol{\Lambda}|^{1/2} \exp \left\{ -\frac{1}{2} \left( \mathbf{x}^\top \boldsymbol{\Lambda} \mathbf{x} + \boldsymbol{\xi}^\top \boldsymbol{\Lambda}^{-1} \boldsymbol{\xi} - 2\mathbf{x}^\top \boldsymbol{\xi} \right) \right\}$$

where  $\boldsymbol{\Lambda} = \boldsymbol{\Sigma}^{-1}$  and  $\boldsymbol{\xi} = \boldsymbol{\Sigma}^{-1} \boldsymbol{\mu}$  are the “natural parameters” (more when we discuss exp. family).

- Note that there is a term **quadratic in  $\mathbf{x}$**  (involves  $\boldsymbol{\Lambda} = \boldsymbol{\Sigma}^{-1}$ ) and **linear in  $\mathbf{x}$**  (involves  $\boldsymbol{\xi} = \boldsymbol{\Sigma}^{-1} \boldsymbol{\mu}$ )



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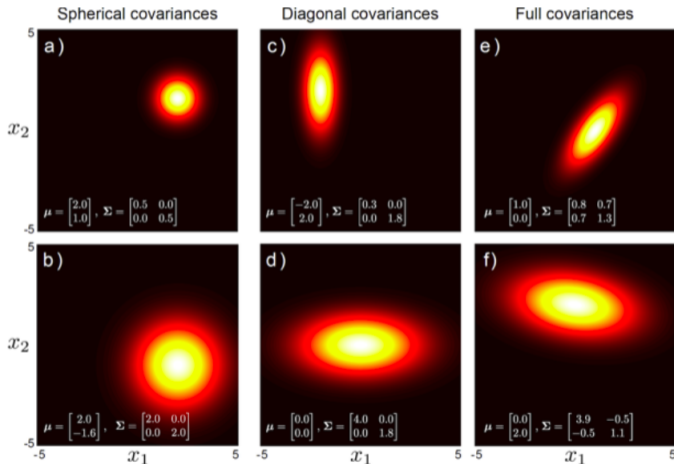
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- Information form can help recognize  $\boldsymbol{\mu}$  and  $\boldsymbol{\Sigma}$  of a Gaussian when doing algebraic manipulations



# Multivariate Gaussian: The Covariance Matrix

The covariance matrix can be spherical, diagonal, or full



Picture courtesy: Computer vision: models, learning and inference (Simon Price)



# Marginals and Conditionals from Gaussian Joint Distribution

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- Both results are **extremely useful** when working with Gaussian joint distributions



# An Aside: Linear Transformations of Random Variables

- Suppose  $\mathbf{x} = f(\mathbf{z}) = \mathbf{A}\mathbf{z} + \mathbf{b}$  be a linear function of an r.v.  $\mathbf{z}$  (not necessarily Gaussian)
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- These properties are often helpful in obtaining the marginal distribution  $p(\mathbf{x})$  from  $p(\mathbf{z})$



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- Likewise if  $x = f(\mathbf{z}) = \mathbf{a}^T \mathbf{z} + b$  is a scalar-valued linear function of an r.v.  $\mathbf{z}$ :
  - $\mathbb{E}[x] = \mathbb{E}[\mathbf{a}^T \mathbf{z} + b] = \mathbf{a}^T \boldsymbol{\mu} + b$
  - $\text{var}[x] = \text{var}[\mathbf{a}^T \mathbf{z} + b] = \mathbf{a}^T \boldsymbol{\Sigma} \mathbf{a}$
- These properties are often helpful in obtaining the marginal distribution  $p(\mathbf{x})$  from  $p(\mathbf{z})$



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- Exercise:** Prove the above two results (MLAPP Chap. 4 and PRML Chap. 2 contain the proof)



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