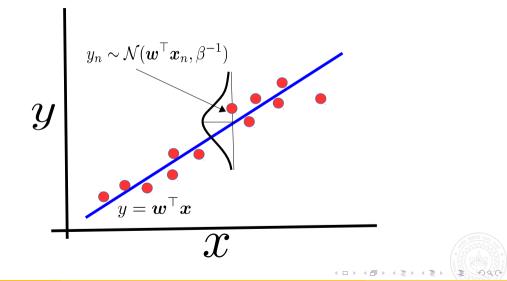
Probabilistic Models for Supervised Learning (Contd.)

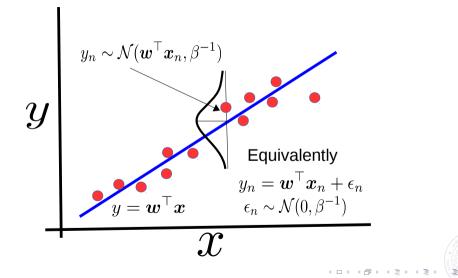
Piyush Rai

Introduction to Machine Learning (CS771A)

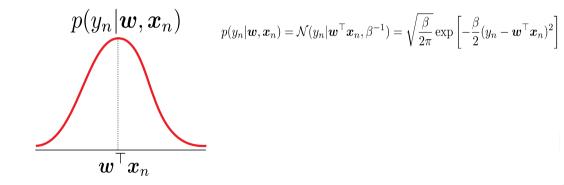
August 21, 2018

Intro to Machine Learning (CS771A)

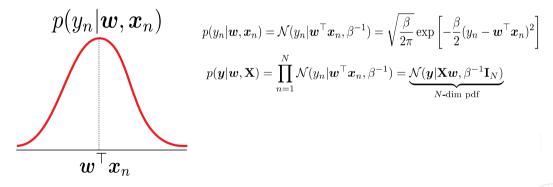




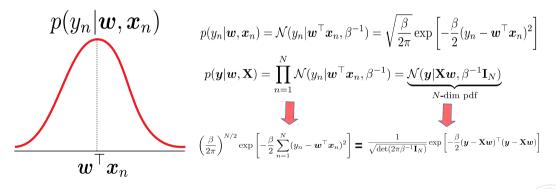
The Likelihood

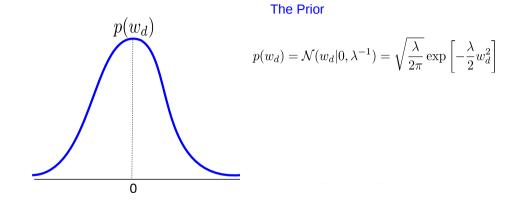


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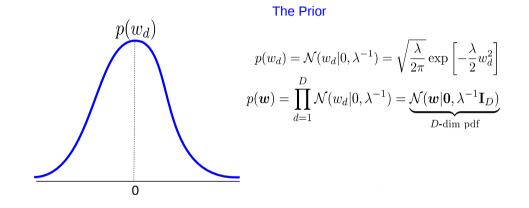
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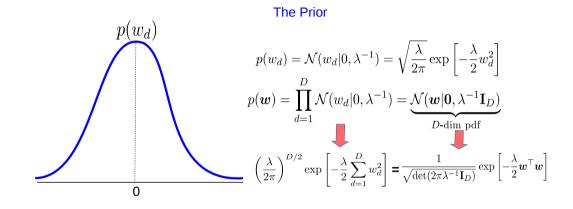


Zero-mean Gaussian prior encourages weights to be small. Precision λ controls how strong this prior is.

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• For MLE, we maximize the log-likelihood. Ignoring constants w.r.t. \boldsymbol{w} , we have

$$\hat{\boldsymbol{w}}_{MLE} = \arg \max_{\boldsymbol{w}} \log p(\boldsymbol{y}|\boldsymbol{X}, \boldsymbol{w})$$



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• For Bayesian inference, we compute the full posterior. Easily computable (thanks to conjugacy)

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$$\boldsymbol{\mu}_{N} = (\boldsymbol{X}^{\top}\boldsymbol{X} + \frac{\lambda}{\beta}\boldsymbol{I}_{D})^{-1}\boldsymbol{X}^{\top}\boldsymbol{y}$$

• When using MLE/MAP estimate of w, we compute the "plug-in" predictive distribution

$$p(y_*|\mathbf{x}_*, \mathbf{X}, \mathbf{y}) \approx p(y_*|\mathbf{x}_*, \mathbf{w}_{MLE}) = \mathcal{N}(\mathbf{w}_{MLE}^\top \mathbf{x}_*, \beta^{-1})$$

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$$\begin{aligned} p(y_*|\mathbf{x}_*,\mathbf{X},\mathbf{y}) &\approx p(y_*|\mathbf{x}_*,\mathbf{w}_{MLE}) &= \mathcal{N}(\mathbf{w}_{MLE}^\top\mathbf{x}_*,\beta^{-1}) \\ p(y_*|\mathbf{x}_*,\mathbf{X},\mathbf{y}) &\approx p(y_*|\mathbf{x}_*,\mathbf{w}_{MAP}) &= \mathcal{N}(\mathbf{w}_{MAP}^\top\mathbf{x}_*,\beta^{-1}) \end{aligned}$$

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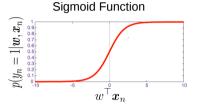
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For Bayesian approach, mean of predicted output is *w_N^Tx_{*}*, variance is β⁻¹ + *x_{*}^TΣ_Nx_{*}*(note the different variance for each test input, unlike MLE/MAP prediction)

• Logistic Regression models $p(y_n = 1 | \boldsymbol{w}, \boldsymbol{x}_n)$ using the sigmoid function

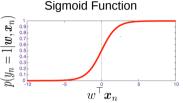
$$p(y_n = 1 | \boldsymbol{w}, \boldsymbol{x}_n) = \mu_n = \sigma(\boldsymbol{w}^\top \boldsymbol{x}_n) = \frac{1}{1 + \exp(-\boldsymbol{w}^\top \boldsymbol{x}_n)} = \frac{\exp(\boldsymbol{w}^\top \boldsymbol{x}_n)}{1 + \exp(\boldsymbol{w}^\top \boldsymbol{x}_n)}$$





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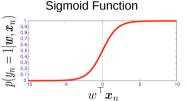
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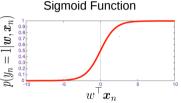


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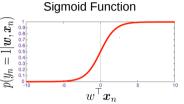
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- Can also use a Gaussian prior $p(w) = \mathcal{N}(w|\mathbf{0}, \lambda^{-1}\mathbf{I}_D)$ just like in probabilistic linear regression
- Can estimate \boldsymbol{w} via MLE, MAP, or (a somewhat hard to do) fully Bayesian inference

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• Logistic regression can be extended to more than 2 classes

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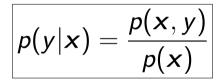
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Generative Models for Supervised Learning



Here, we will model both inputs and outputs!

Generative Classification

• Consider a classification problem with $K \ge 2$ classes



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Intro to Machine Learning (CS771A)

- \bullet Consider a classification problem with ${\cal K} \geq 2$ classes
- \bullet Assuming θ to collectively denote all the params, the generative classification model is

$$p(y = k | \mathbf{x}, \theta) = \frac{p(\mathbf{x}, y = k | \theta)}{p(\mathbf{x} | \theta)}, \quad k = 1, \dots, K$$

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 - $p(\mathbf{x}|\mathbf{y} = \mathbf{k}, \theta)$: The class-conditional distribution of the inputs

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• Note that the denominator $p(\mathbf{x}|\theta) = \sum_{k=1}^{K} p(\mathbf{x}, y = k|\theta)$, using sum rule of probability

• Can use the chain rule to re-express the above as

$$p(y = k | \mathbf{x}, \theta) = \frac{p(y = k | \theta) p(\mathbf{x} | y = k, \theta)}{p(\mathbf{x} | \theta)}$$

- This depends on two quantities
 - $p(y = k|\theta)$: The class-marginal distribution (also called "class prior")
 - $p(\mathbf{x}|\mathbf{y} = \mathbf{k}, \theta)$: The class-conditional distribution of the inputs
- Generative classification requires first estimating the parameters θ of these two distributions

• Estimating the class-marginal is usually straightforward in generative classification



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- The class marginal distribution is (has to be!) a discrete distribution (multinoulli)

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multinoulli $(y|\pi_1, \dots, \pi_K) = \prod_{k=1}^K \pi_k^{\mathbb{I}[y=k]}$



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• Given N labeled training examples $\{(x_n, y_n)\}_{n=1}^N$, MLE for π (won't depend on x_n 's) will be

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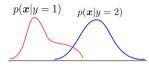
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- Note: If MAP (or full posterior) is needed, we can use a Dirichlet prior distribution on π
 - Another exercise: Try to derive the MAP estimate of π and also the full posterior (good news: multinoulli and Dirichlet are conjugate to each other, so full posterior is easy)

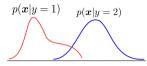
Intro to Machine Learning (CS771A)



• We usually assume an appropriate class-conditional $p(\mathbf{x}|y = k, \theta)$ for the inputs, e.g.,

- If $\mathbf{x} \in \mathbb{R}^{D}$, then a *D*-dim Gaussian $\mathcal{N}(\mathbf{x}|\boldsymbol{\mu}_{k}, \boldsymbol{\Sigma}_{k})$ may be appropriate (here $\theta = (\boldsymbol{\mu}_{k}, \boldsymbol{\Sigma}_{k})$)
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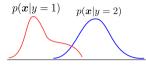
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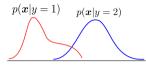
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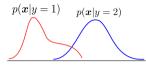
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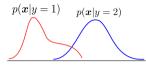
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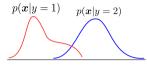
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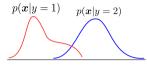
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• Suppose we've estimated the parameters of $p(y = k|\theta)$ and $p(x|y = k, \theta)$ (assuming MLE/MAP)



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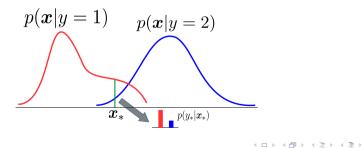
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• If p(y = k) is the same for all the classes then, we simple compare $p(\mathbf{x}|y = k)$



Intro to Machine Learning (CS771A)

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 - We also saw estimation of π_k 's. ($\mu_k, \mathbf{\Sigma}_k$) can be found via Gaussian parameter estimation
- If using MLE/MAP estimate of θ , the predictive distribution will be

$$p(\mathbf{y}_{*} = k | \mathbf{x}_{*}, \theta) = \frac{\pi_{k} | \mathbf{\Sigma}_{k} |^{-1/2} \exp \left[-\frac{1}{2} (\mathbf{x}_{*} - \boldsymbol{\mu}_{k})^{\mathsf{T}} \mathbf{\Sigma}_{k}^{-1} (\mathbf{x}_{*} - \boldsymbol{\mu}_{k}) \right]}{\sum_{k=1}^{K} \pi_{k} | \mathbf{\Sigma}_{k} |^{-1/2} \exp \left[-\frac{1}{2} (\mathbf{x}_{*} - \boldsymbol{\mu}_{k})^{\mathsf{T}} \mathbf{\Sigma}_{k}^{-1} (\mathbf{x}_{*} - \boldsymbol{\mu}_{k}) \right]}$$

Decision Boundaries

• The generative classification prediction rule we saw had

$$p(y=k|\mathbf{x},\theta) = \frac{\pi_k |\mathbf{\Sigma}_k|^{-1/2} \exp\left[-\frac{1}{2}(\mathbf{x}-\boldsymbol{\mu}_k)^\top \mathbf{\Sigma}_k^{-1}(\mathbf{x}-\boldsymbol{\mu}_k)\right]}{\sum_{k=1}^K \pi_k |\mathbf{\Sigma}_k|^{-1/2} \exp\left[-\frac{1}{2}(\mathbf{x}-\boldsymbol{\mu}_k)^\top \mathbf{\Sigma}_k^{-1}(\mathbf{x}-\boldsymbol{\mu}_k)\right]}$$



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• The decision boundary between any pair of classes will be..

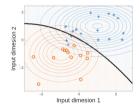


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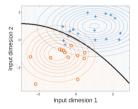
• The decision boundary between any pair of classes will be.. a quadratic curve



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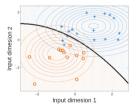
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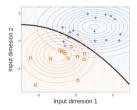
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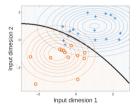
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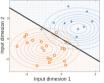
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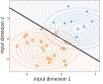


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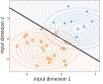
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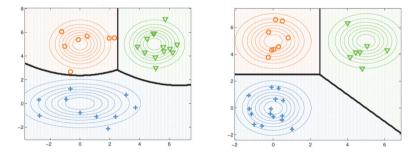


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.. terms quadratic in x cancel out in this case and we get a linear function of x (this model is popularly known as Linear or "Fisher" Discriminant Analysis)

• Depending on the form of the covariance matrices, the boundaries can be quadratic/linear



• For the linear case (when $\Sigma_k = \Sigma$), we have

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• Interestingly, this has exactly the same form as the softmax classification model (saw it in last class), which is a discriminative model, as opposed to a generative model.

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 - The covariance matrix "modulates" how the distances are computed

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- Generative models are also useful for unsupervised and semi-supervised learning (will look at later)

• Estimating the class-conditional distributions $p(\mathbf{x}|\mathbf{y})$ reliably is important



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- MLE for parameter estimation in these models can be prone to overfitting



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- A good density estimation model is necessary for generative classification model to work well

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• Note: Can use generative models for doing regression as well (will be an exercise)