

# Grid Graph Reachability in UL

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**Graph reachability characterizes various classes. In particular, the directed graph reachability is known to be NL-complete while undirected graph reachability is known to be in L.**

## Our job:

### **Show Directed Planar Reachability in UL**

#### *Proof Idea:*

- Reduce Directed Planar Reachability to Grid Graph Reachability.
- Show that Grid Graph Reachability is in UL.
  - a. Reduce grid graph reachability to min-unique reachability.
  - b. Show that min-unique reachability is in UL.

## **Grid Graph:**

$N \times N$  graph such that the following holds:

If there is an edge from  $(x_1, y_1)$  to  $(x_2, y_2)$ ,

- a.  $x_1 = x_2$  and  $|y_1 - y_2| = 1$
- b.  $y_1 = y_2$  and  $|x_1 - x_2| = 1$ .

### Min-unique graph :

- Directed Graph with weighted edges.
- Weight of a path is sum of weights of edges.
- If there is a path from  $u$  to  $v$ , then there is a unique minimum weight path from  $u$  to  $v$ .

***Theorem (Reinhardt and Allender [3]).*** Let  $G$  be a class of graphs and let  $H = (V, E) \in G$ . If there is a polynomially-bounded log-space computable function  $f$  that on input  $H$  outputs a weighted graph  $f(H)$  so that

1.  $f(H)$  is min-unique, and
2.  $H$  has an  $st$ -path if and only if  $f(H)$  has an  $st$ -path. Then the  $st$ -connectivity problem for  $G$  is in UL

*We first show an easier result.*

**Layered Grid Graph reachability is in UL.**

## Layered Grid Graph:

$N \times N$  graph such that the following holds:

If there is an edge  $(x_1, y_1)$  to  $(x_2, y_2)$ ,

- a.  $x_1 = x_2$  and  $y_2 - y_1 = 1$ .
- b.  $y_1 = y_2$  and  $x_2 - x_1 = 1$ .



Layered grid graph-**Weight function**:

$W(e)=x$  if edge from  $(x,y) \rightarrow (x,y+1)$

$W(e)=0$  if edge from  $(x,y) \rightarrow (x+1,y)$ .

**Note the following:**

The path is simple, due to the restrictions on the graph.

Weight cannot be same.

*We now move to the case of the general grid graph reachability problem.*

## *Determining if $d(v) \leq k$ or not*

Input:  $(G, v, k, c_k, \sum_k)$

Output: true if  $d(v) \leq k$  else false

```
1 Initialize count  $\leftarrow$  0; sum  $\leftarrow$  0; path.to.v  $\leftarrow$  false
2 foreach  $x \in V$  do
3     Nondeterministically guess if  $d(x) \leq k$ 
4     if guess is Yes then
5         Guess a path of length  $l \leq k$  from  $s$  to  $x$ 
6         if guess is correct then
7             Set count  $\leftarrow$  count + 1
8             Set sum  $\leftarrow$  sum + 1
9             if  $x = v$  then set path.to.v  $\leftarrow$  true
10        Else
11            return “?”
12    End
13 End
14 End

15 if count =  $c_k$  and sum =  $\sum_k$  then
16     return path.to.v
17 Else
18     return “?”
19 end
```

## Computing $c_k$ and $\Sigma_k$

Input:  $(G, k, c_{k-1}, \Sigma_{k-1})$

Output:  $c_k, \Sigma_k$

1 Initialize  $c_k \leftarrow c_{k-1}$  and  $\Sigma_k \leftarrow \Sigma_{k-1}$

2 foreach  $v \in V$  do

3     if  $\neg(d(v) \leq k - 1)$  then

4         foreach  $x$  such that  $(x, v) \in E$  do

5             if  $d(x) \leq k - 1$  then

6                 Set  $c_k \leftarrow c_{k+1}$

7                 Set  $\Sigma_k \leftarrow \Sigma_k + k$

8             end

9         end

10     end

11 end

12 return  $c_k$  and  $\Sigma_k$

### *Weight function*

$W(e) = n^4$  if  $e$  is an edge from  $(x_1, y) \rightarrow (x_2, y)$  where  $|x_2 - x_1| = 1$   
 $x + n^4$  if  $e$  is an edge from  $(x, y) \rightarrow (x, y + 1)$   
 $-x + n^4$  if  $e$  is an edge from  $(x, y) \rightarrow (x, y - 1)$ .

Positive weight edges imply simple path

### **Uniqueness of path:**

Weight of path can be divided into two components  $C(p) + n^4D(p)$ .

$D(p)$  would denote the number of edges on the path.

# Weight of a cycle

For a simple cycle, we show the following:

The weight of the path is:

$A(C)$  in case of a counter-clockwise path

$-A(C)$  in case of a clockwise path

$A(C)$  is the number of blocks enclosed by the simple cycle.





References:

[1]-Chris Bourke, Raghunath Tewari and N.V. Vinodchandran, Directed Planar Reachability is in Unambiguous Logspace.

[2]-The Directed Planar Reachability by Eric Allender, Samir Datta, Sambhudha Roy

[3]- Klaus Reinhardt and Eric Allender, Making nondeterminism unambiguous, SIAM Journal of Computing, 29 (2000), pp. 1118–1131.