

- Thus, the question $NP \stackrel{?}{=} PSPACE$ is asking whether "games" are harder than "puzzles"!

- Using the proof of the previous theorem we can also show $NpSpace = Pspace$.

Theorem (Savitch 1970): $Nspace(S) \subseteq Space(S^2)$.

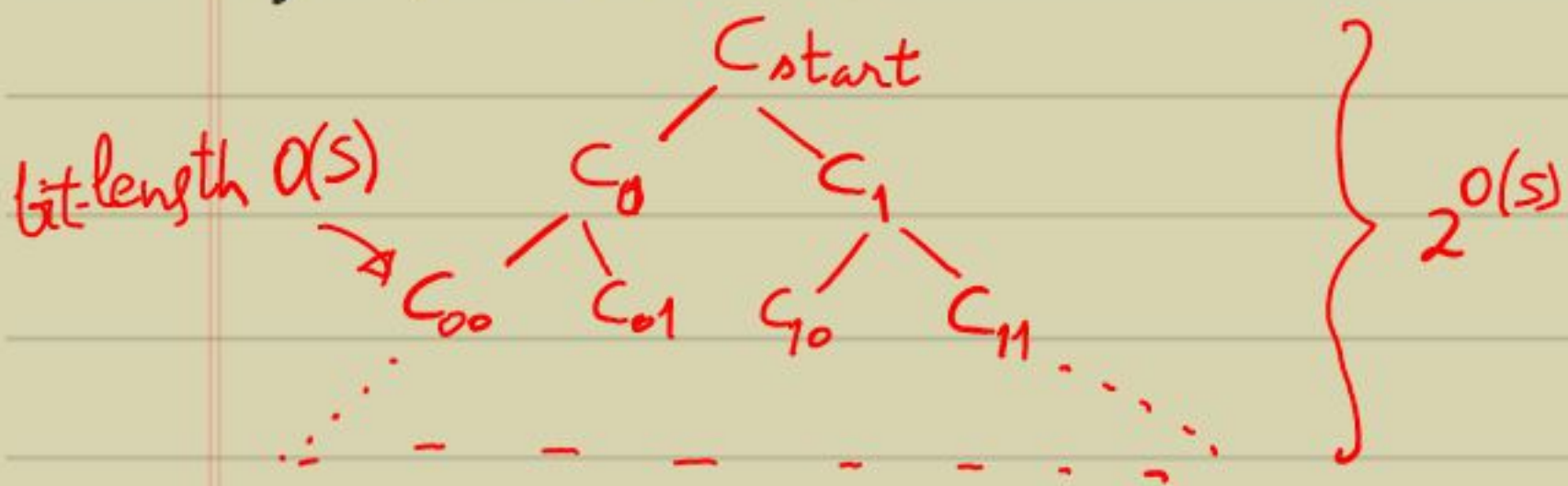
Proof:

- Let M be an $S(n)$ -space NDTM deciding $L \in Nspace(S)$.
- As in the proof of Lemma 2, we design a QBF: $\Psi_{M,x} = \Psi_{d \cdot S(n)}(C_{start}, C_{accept})$,
with x

with the modification that $\Phi_{M,x}(C, C')$ captures two possible transition steps instead of a unique one.

- $\Psi_{M,x}$ remains a QBF of size $O(S^2)$.
- So, easily checkable in $Space(S^2)$. \square

- Another way to interpret the previous result is through the configuration's tree of the NDTM M :



▷ Each configuration requires $O(S)$ space & specifying a location in the tree requires $\lg 2^{O(S)}$ space.

\Rightarrow Reachability $C_{start} \rightsquigarrow C_{stop}$ can be checked in $O(S^2)$ space.

(Alternately, do it in $2^{O(S)}$ time & space!)

- Reachability also plays an important role in the "small" classes NL, L, \dots

NL-completeness

- By the previous discussion
 $\mathbb{L} \subseteq NL \subseteq P$.

- For a meaningful notion of "hardness" in NL we need \mathbb{L} -reductions.

Defn: • We call $f: \{0,1\}^* \rightarrow \{0,1\}^*$ implicitly \mathbb{L} -computable if
 $L_f := \{(x, i) \mid f(x)_i = 1\}$, &
 $L'_f := \{(x, k) \mid |f(x)| \geq k\}$
are in \mathbb{L} .

• We call $A \leq_{\mathbb{L}} B$ if \exists implicitly \mathbb{L} -computable f s.t. $\forall x \in \{0,1\}^*$,
 $x \in A$ iff $f(x) \in B$.

• We call B NL-complete if
 $B \in NL$, &
 $\forall A \in NL, A \leq_{\mathbb{L}} B$.

Proposition: (i) $A \leq_{\mathbb{L}} B \leq_{\mathbb{L}} C \Rightarrow A \leq_{\mathbb{L}} C$.

(ii) $A \leq_{\mathbb{L}} B$ & $B \in \mathbb{L} \Rightarrow A \in \mathbb{L}$.

Proof:

(i) Let f, g be the two implicitly \mathbb{L} -computable fns. Observe that $g \circ f$ is also implicitly \mathbb{L} -computable.

(ii) Similar. \square

- We now see an NL-complete problem.

Defn: Path := $\{(G, s, t) \mid \exists \text{ directed path } s \rightsquigarrow t \text{ in the directed graph } G\}$.

Lemma 1: $\text{Path} \in \text{NL}$.

Pf: • Let (G, s, t) be an input instance.

• Each vertex in G can be identified in $\log |G|$ space.

• Thus, an NDTM M that simulates a walk in G (with origin s & accepts on reaching t),

has space complexity $O(\log n)$.

$\Rightarrow \text{Path} \in \text{NL}$. \square

Lemma 2: $\forall A \in \text{NL}, A \leq_{\text{NL}} \text{Path}$,

Proof:

• Let M be an NDTM deciding A in space $\leq d \cdot \log n$.

• We consider an f that maps an input x of A to $f(x) = (G, s, t)$ where G is the configuration graph of $M(x)$:

(1) the vertices of G are all the configs. of $M(x)$,

(2) s & t are the "start" & "accept" configs. respectively,

(3) the edge (C, C') is there iff $C \rightarrow C'$ is a valid transition step of $M(x)$.

• Obviously, $x \in A$ iff $f(x) \in \text{Path}$.

• More importantly, f is implicitly \mathbb{L} -computable:

- (1) the list of vertices is \mathbb{L} -computable,
- (2) given (C, C') we can check whether it's a valid transition of $M(x)$ in $O(|C| + |C'|) = O(\log|x|)$ space.

(Basically, scan C, C' & refer the δ -fn. of the TM M .) \square

Theorem: Path is NL-complete.

Open: $NL \neq \mathbb{L}$?

Corollary: $\overline{\text{Path}}$ is coNL-complete.

Pf: • Use the same f as before. \square

Qn: Is $NL = \text{coNL}$?