

- Another example of augmented AVL tree:

## Orthogonal Range Searching

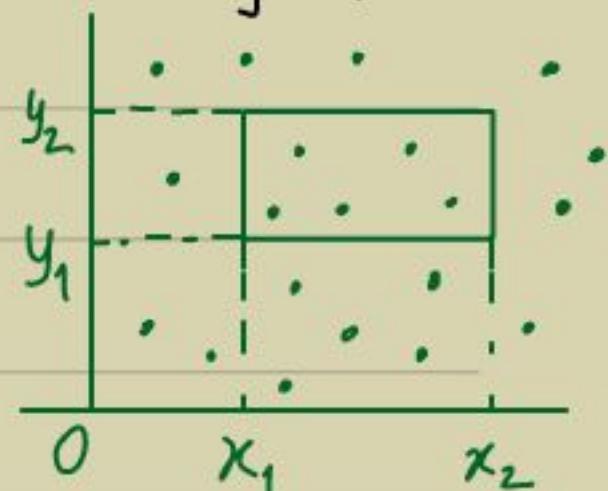
- Input: A set of points  $T \subset \mathbb{R}^2$  & a rectangle  $(x_1, y_1, x_2, y_2) =: R$ .

Output: All points in the rectangle, ie.  $T \cap R$ .

- Brute-force: It can be solved in  $O(n)$  time.

Qn: Can it be done significantly faster?

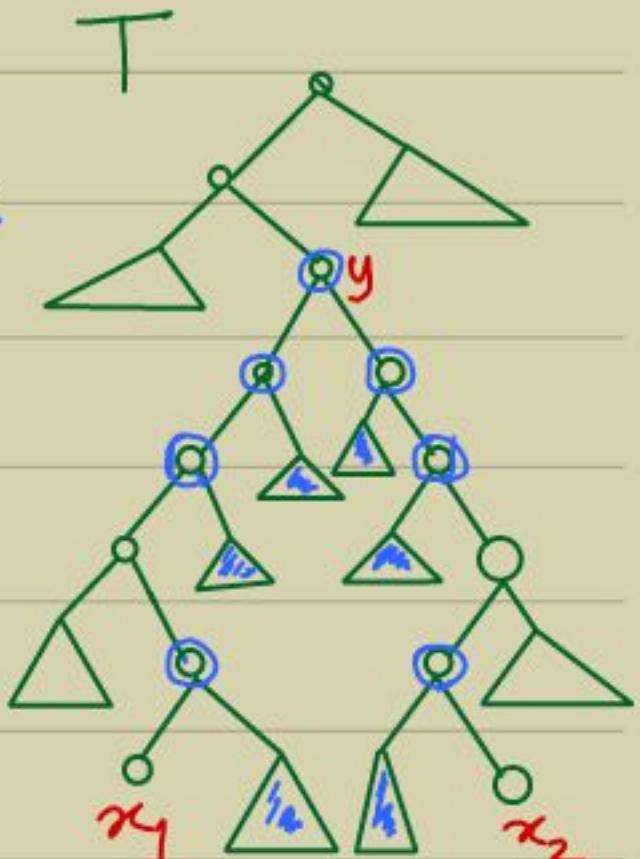
$$\text{Let } k := |T \cap R|.$$



- Easier question: Find the points on the line  $(x_1, x_2)$ ?

- Store the points in an AVL tree wrt the  $x$ -coordinate.
- Search  $x_1, x_2$  in  $T$  & find the least common ancestor (lca)  $y$ .

▷ In the tree  $T$  the blue shaded nodes are exactly the points in  $[x_1, x_2]$ .



▷ If  $|T \cap [x_1, x_2]| =: l$  then these points can be found in  $O(l + \lg n)$  time.

- Next, how do we find the points in  $T \cap R$ ?

- Ans: Augment each node  $v$  by adding another copy of  $\text{tree}(v)$  as: An AVL tree organized wrt y-coordinates.

Call this  $y\text{tree}(v)$ .

- This inspires the following pseudocode for  $\text{RangeSearch}(T, x_1, x_2, y_1, y_2)$ :

- For root  $v$  of each blue shaded subtree {

We may make  $O(\lg n)$  such calls. → Do  $\text{RangeSearch}(y\text{tree}(v), y_1, y_2)$  }

- For the other blue vertices  $v$  on the

search path: Check whether  $v \in T \cap R$ .

- Output the ones found in  $T \cap R$ .

▷ Orthogonal Range Search can be done in  $O(k + \lg^2 n)$  time.

Pf: (Exercise)

□

- Note that preprocessing time taken is  $O(n \lg n)$ .

But, the query time is significantly lower!

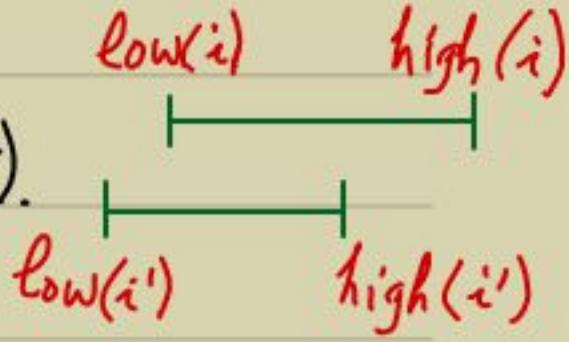
- Note that the space required by the augmented AVL tree is  $\approx$

$$\sum_{v \in T} |\text{tree}(v)| = \sum_{u \in T} \#(v \in T : v \text{ is an ancestor of } u)$$

$$\leq |T| \cdot \text{depth}(T)$$

$$= O(n \lg n).$$

## Interval Trees

- Computational geometry, or scheduling, problems require organization of intervals.
- Interval  $i = [t_1, t_2]$  has the low endpoint  $t_1 = \text{low}(i)$  & high endpoint  $t_2 = \text{high}(i)$ .
- Interval  $i, i'$  overlap if  $i \cap i' \neq \emptyset$ .  
Equivalently,  
 $\text{low}(i) \leq \text{high}(i') \& \text{low}(i') \leq \text{high}(i)$ .
- Qn: Is there a data structure where an overlapping interval can be searched in  $O(\lg n)$  time? (given an  $i$ )
- Ans: Let  $T$  be the set of  $n$  intervals.  
Organize  $T$  into an AVL tree wrt the low endpoints,

- We now need to implement:
  - 1) Insert( $T, i$ ): insert  $i$  into  $T$ .
  - 2) Delete( $T, i$ ): delete  $i$  from  $T$ .
  - 3) Search( $T, i$ ): return a pointer to a node  $x \in T$  that overlaps with  $i$ .

- To search for  $i$ , just having  $\text{low}(v)$ , in every node  $v \in T$ , is not enough.

Augmented AVL      We also store max(v) := the maximum value across all the intervals in tree( $v$ ).

Example: Searching for  $[30, 30]$  fails if  $T$  is not augmented!

▷ Insert( $T, i$ ) can be done in  $O(\lg n)$  time.

Pf:

One needs to change  $\text{max}(v)$  in only  $\text{depth}(T)$  many ancestors, while inserting  $i$ . \*

▷ Similarly, for Delete( $T, i$ ).

\* Not a BST wrt  $\text{max}(v)$ .

- The pseudocode for  $\text{Search}(T, i)$  is mainly guided by " $\text{low}(i) \leq \max(\text{left}(v))$ :

- $v \leftarrow \text{root}(T);$
- while ( $i$  does not overlap  $\text{int}(v)$ ) {  
*high(i) → not used?*
  - if ( $\text{low}(i) \leq \max(\text{left}(v))$ )  
then  $v \leftarrow \text{left}(v);$
  - else  $v \leftarrow \text{right}(v);$  }
- return  $v;$

- Caution: Handle the boundary conditions like -  $v = \text{NULL}$  or  $\text{left}(v) = \text{NULL}$  or  $\text{right}(v) = \text{NULL}$ .

Exercise: Show that it correctly finds a  $v \in T$  s.t.  $\text{int}(v) \cap i \neq \emptyset$  in  $O(\lg n)$  time.

Hint 1: Loop invariant - If  $i$  overlaps with some interval in  $T$ , then " " " " "  
" " tree( $v$ ).

Hint 2: If  $\text{low}(i) \leq \max(\text{left}(v))$  &  $i$  overlaps with some interval in  $\text{tree}(v)$ , then  $i$  overlaps with someone in  $\text{left}(v)$ .

Proof:

- Otherwise, it means that  $\forall u \in \text{left}(v)$ ,  $i \cap \text{int}(u) = \emptyset$ .

$$\Rightarrow \text{low}(i) > \text{high}(\text{int}(u)) \text{ OR}$$

$$\text{high}(i) < \text{low}(\text{int}(u))$$

$$\Rightarrow \exists u \in \text{left}(v), \underline{\text{high}(i)} < \text{low}(\text{int}(u)) \quad [\because \text{low}(i) \leq \max(\text{left}(v))]$$
$$\Rightarrow \underline{\text{low}(i)} < \underline{\text{high}(i)} < \text{low}(\text{int}(u)).$$

- This means that  $\underline{\text{high}(i)} < \text{low}(\text{int}(u))$ ,  $\forall u \in \text{tree}(\text{right}(v)) \cup \{v\}$ . [ $\because T$  uses low endpoints]
- Hence,  $i$  does not overlap with any interval in  $\text{tree}(v)$ .  $\square$

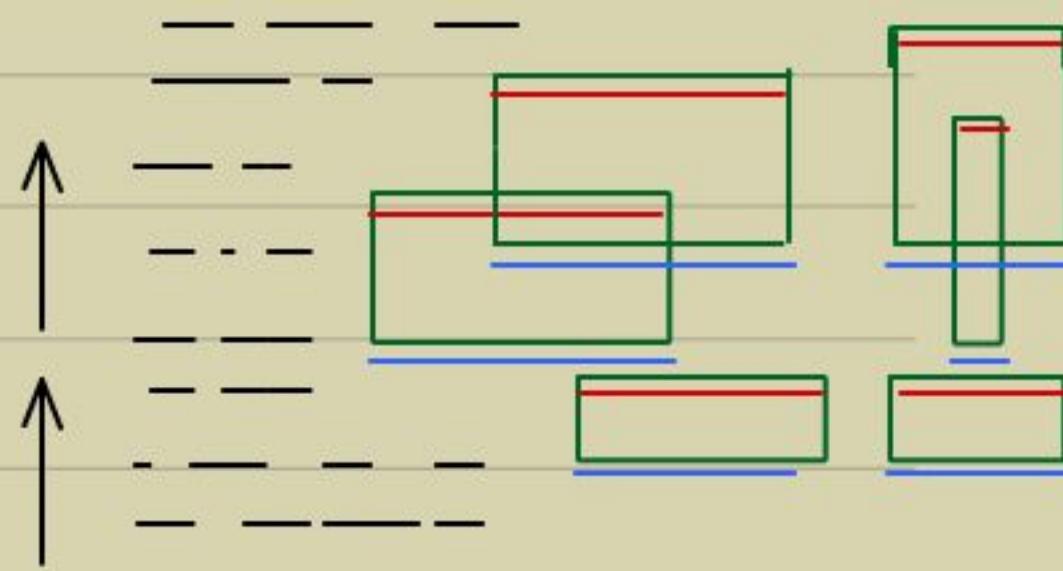
! It's a tricky proof, as it deduces a lot about  $\text{high}(i)$  !

# Apply to Rectangle Overlap

- Input: A list  $L$  of axis-parallel rectangles ( $n$  of them via  $2n$  points).
- Output: YES if two of them overlap

Qn: Can you solve in time less than  $O(n^2)$ ?

- Idea: (Virtual line sweep!)
  - Order the red & blue edges w.r.t y-coordinates in an array A.
  - Pick an edge  $e$  from  $A$ , in order.
  - If  $e$  is blue: Check whether  $e$  overlaps with an edge in an interval tree T; if no, Insert( $T, e$ ).



- If  $e$  is red: Let  $e'$  be the associated blue edge. Search & Delete  $e'$  from  $T$ . If  $e' \notin T$  then OUTPUT OVERLAP. Else goto the next  $e$  in  $A$ .

Exercise: Write the pseudocode & prove that it works in time  $O(n \lg n)$ .

- Invariant 1:  $T$  has non-overlapping blue intervals with their reds yet to be swept.
- Invariant 2: Unmatched red means an overlap.

- Eg. B R B R

Eg. B B R R

Eg. B B R R