Parallel Programming models in the era of multi-core processors:

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Requirements

- Composibility
- Respect for locality
- Dealing with heterogeneity
- Dealing with the memory wall
- Dealing with dynamic resource variation
 - Machine running 2 parallel apps on 64 cores, needs to run a third one
 - Shrink and expand the sets of cores assigned to a job
- Dealing with Static resource variation : *Fwd Scaling*
 - I.e. Parallel App should run unchanged on the next generation manycore with twice as many cores
- Above all: Simplicity

Guidelines

- A guideline that appeals to me:
 - Bottom-up, application-driven development of abstractions
- Aim at a good division of labor between the programmer and System
 - Automate what the system can do well
 - Allow programmer to do what they can do best

Foundation: Adaptive Runtime System

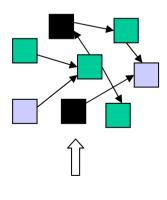
For me, Based on Migratable Objects

Programmer: [Over] decomposition into virtual processors

Runtime: Assigns VPs to processors

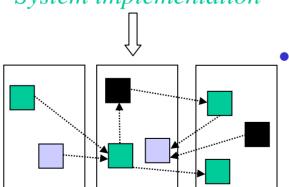
Enables *adaptive runtime strategies*

Implementations: Charm++, AMPI



System implementation

User View



Benefits

- Software engineering
 - Num. of VPs to match application logic (not physical cores)
 - Separate VPs for different modules
- Message driven execution
 - Predictability :
 - Asynchronous reductions
 - Dynamic mapping
 - Heterogeneity
 - Vacate, adjust to speed, share
 - Change set of processors used
 - Dynamic load balancing

What is the cost of Processor Virtualization?

"Overhead" of Virtualization

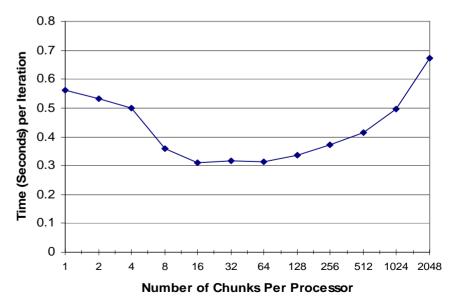
$$T_{1} = T(1 + \frac{v}{g})$$

$$T_{p} = \max(g, \frac{T_{1}}{P})$$

$$T_{p} = \max(g, \frac{T*(1 + \frac{v}{g})}{P})$$

- V: overhead per message
- Tp: p processor completion time
- G: grainsize (computation per message)

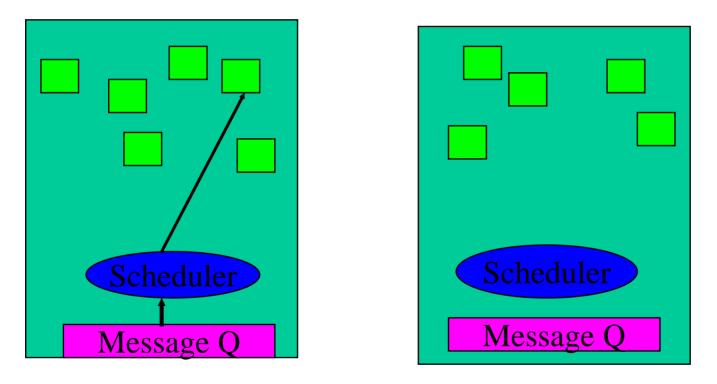
- Fragmentation cost?
 - Cache performance improves
 - Adaptive overlap improves
 - Difficult to see cost..
- Fixable Problems:
 - Memory overhead: (larger ghost areas)
 - Fine-grained messaging:



Modularity and Concurrent Composibility

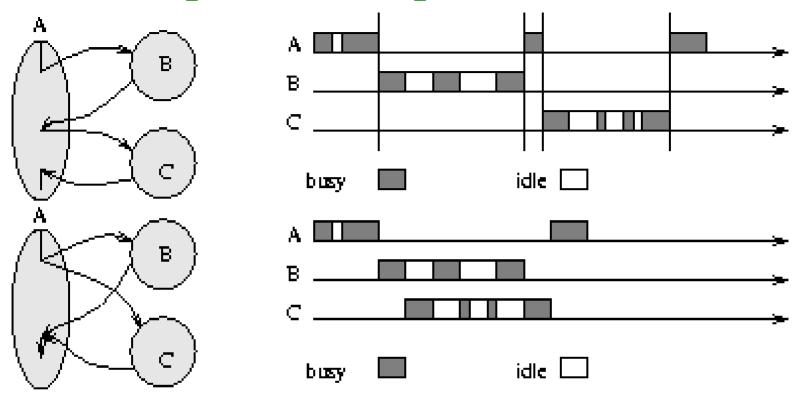
Message Driven Execution

Virtualization leads to Message Driven Execution



Which leads to Automatic Adaptive overlap of computation and communication

Adaptive overlap and modules

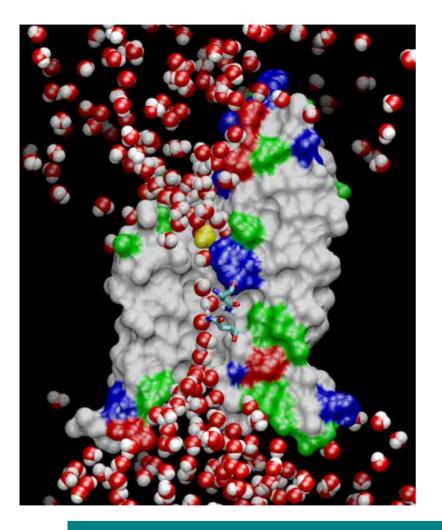


SPMD and Message-Driven Modules

(From A. Gursoy, *Simplified expression of message-driven programs and quantification of their impact on performance*, Ph.D Thesis, Apr 1994.)

Modularity, Reuse, and Efficiency with Message-Driven Libraries: Proc. of the Seventh SIAM Conference on Parallel Processing for Scientific Computing, San Fransisco, 1995

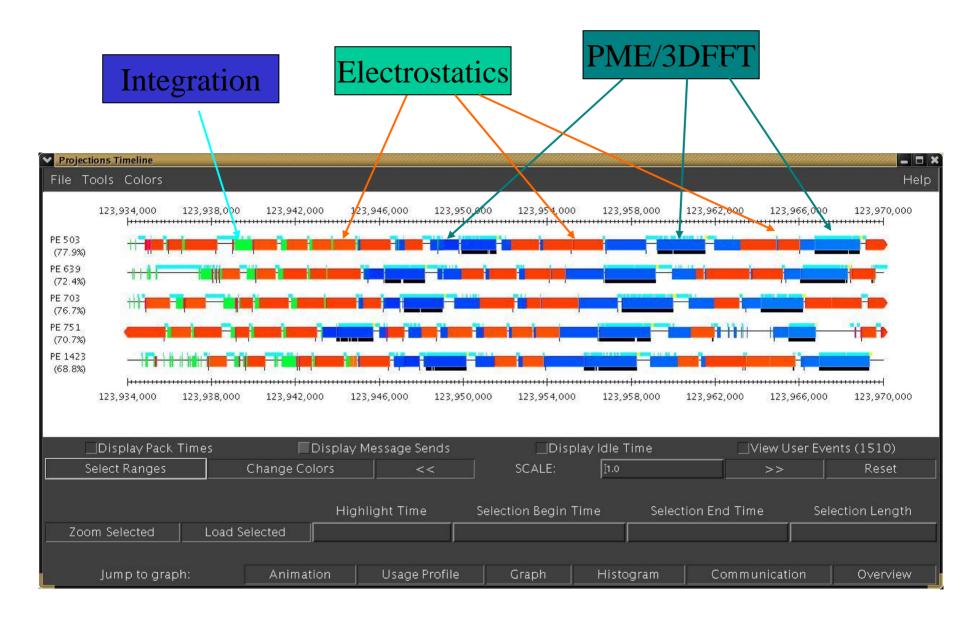
NAMD: A Production MD program



<u>NAMD</u>

- Fully featured program
- NIH-funded development
- Installed at NSF centers
- Large published simulations
- We were able to demonstrate the utility of adaptive overlap, and share the Gordon Bell award in 2002

Collaboration with K. Schulten, R. Skeel, and coworkers



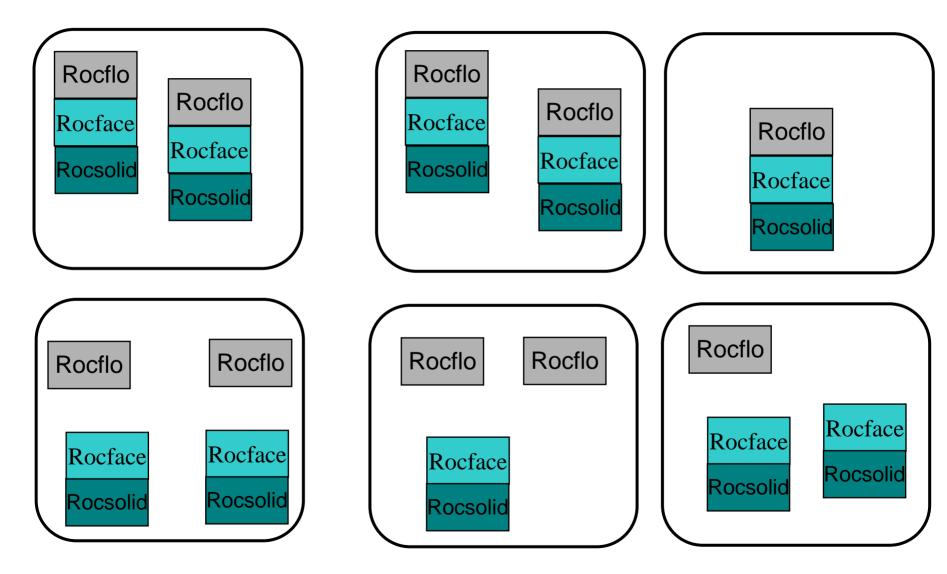
Modularization

- Logical Units decoupled from "Number of processors"
 - E.G. Oct tree nodes for particle data
 - No artificial restriction on the number of processors
 - Cube of power of 2
- Modularity:
 - Software engineering: cohesion and coupling
 - MPI's "are on the same processor" is a bad coupling principle
 - Objects liberate you from that:
 - E.G. Solid and fluid modules in a rocket simulation

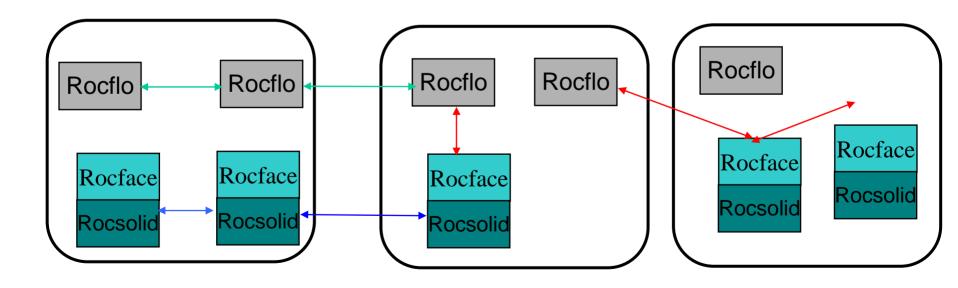
Rocket Simulation

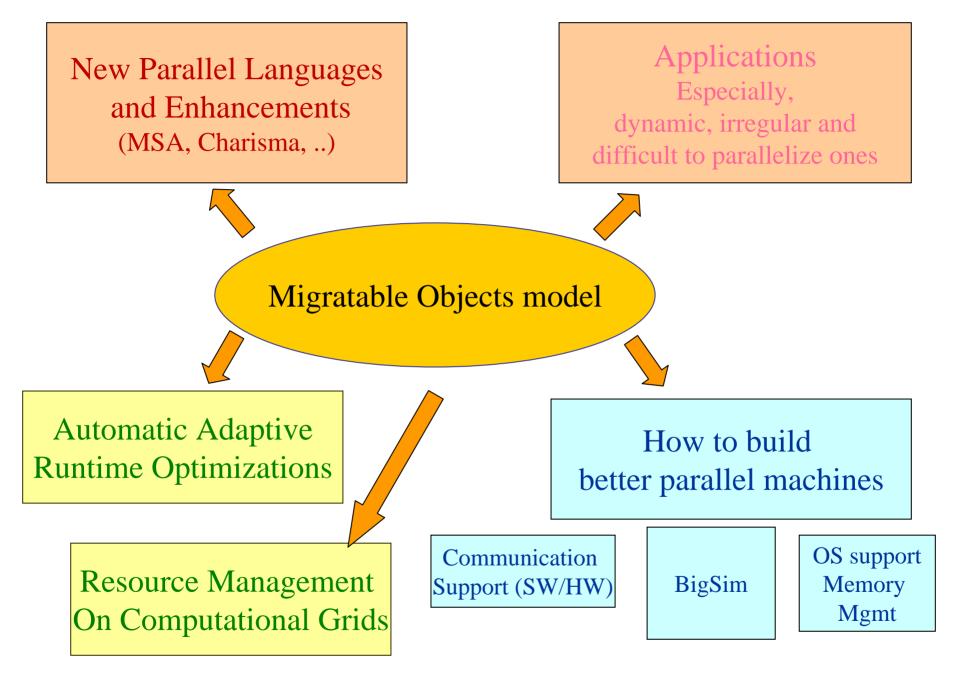
- Large Collaboration headed Mike Heath
 - DOE supported ASCI center
- Challenge:
 - Multi-component code, with modules from independent researchers
 - MPI was common base
- AMPI: new wine in old bottle
 - Easier to convert
 - Can still run original codes on MPI, unchanged

Rocket Simulation Components in AMPI



AMPI and Roc* communications

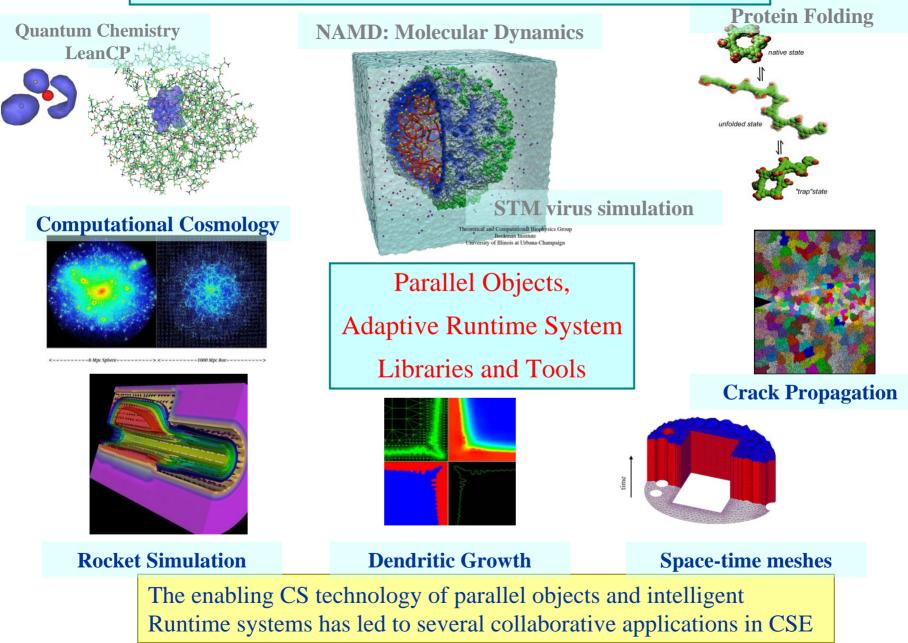




Charm++/AMPI are mature systems

- Available on all parallel machines we know of
 - Clusters, Vendor supported: IBM, SGI, HP (Q), BlueGene/L, ...
- Tools:
 - Performance analysis/visualization
 - Debuggers
 - Live visualization
 - Libraries and frameworks
- Used by many applications
 - 17,000+ installations
 - NAMD, Rocket simulation, Quantum Chemistry, Space-time meshes, animation graphics, Astronomy, ..
- It is C++, with message (event) driven execution
 - So, a familiar model for desktop programmers

Develop abstractions in context of full-scale applications



CSE to ManyCore

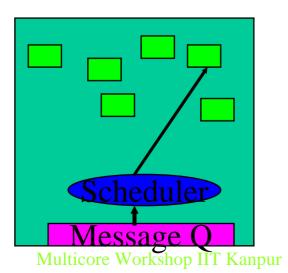
- The Charm++ model has succeeded in CSE/HPC
- Because:
 - Resource management, ...
- In spite of:

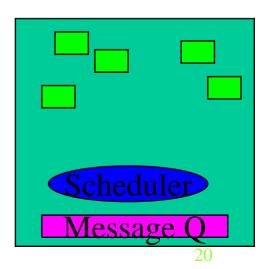
15% of cycles at NCSA,20% at PSC, were usedon Charm++ apps, in aone year period

- Based on C++, not Fortran, message-driven model,..
- But is an even better fit for desktop programmers
 - C++, event driven execution
 - Predictability of data/code accesses

Why is it suitable for Multi-cores

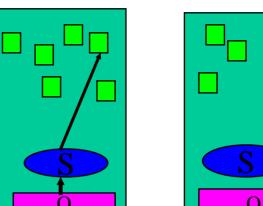
- Objects connote and promote locality
- Message-driven execution
 - A strong principle of prediction for data and code use
 - Much stronger than Principle of locality
 - Can use to scale memory wall:
 - Prefetching of needed data:
 - into scratch pad memories, for example



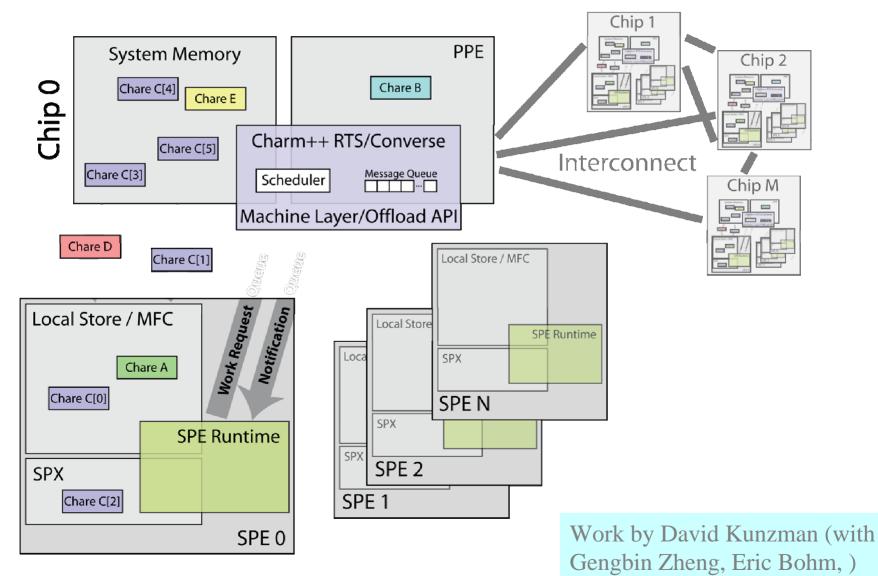


Why Charm++ & Cell?

- Data Encapsulation / Locality
 - Each message associated with...
 - Code : Entry Method
 - Data : Message & Chare Data
 - Entry methods tend to access data local to chare and message
- Virtualization (many chares per proces
 - Provides opportunity to overlap SPE computation with DMA transactions
 - Helps ensure there is always useful work to do
- Message Queue Peek-Ahead / Predictability
 - Peek-ahead in message queue to determine future work
 - Fetch code and data before execution of entry method



System View on Cell

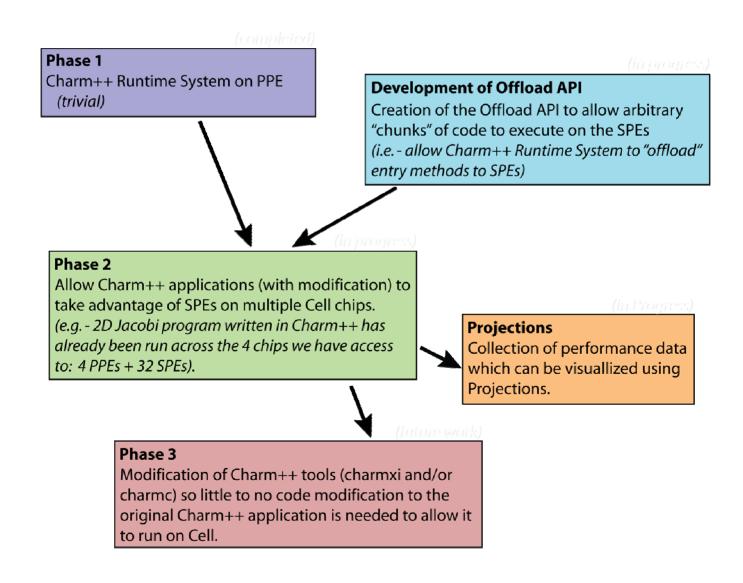


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Multicore Workshop IIT Kanpur

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Charm++ on Cell Roadmap



So, I expect Charm++ to be a strong contender for manycore models

BUT: What about the quest for Simplicity?

Charm++ is powerful, but not much simpler than, say, MPI

How to Get to Simple Parallel Programming Models?

- Parallel Programming is much too complex
 - In part because of resource management issues :
 - Handled by Adaptive Runtime Systems
 - In a larger part, because of unintended non-determinacy
 - Race conditions
- Clearly, we need *simple* models
 - But what are willing to give up? (No free lunch)
 - Give up "Completeness"!?!
 - May be one can design a language that is simple to use, but not expressive enough to capture all needs

Simplicity?

- A collection of "incomplete" languages, backed by a (few) complete ones, will do the trick
 As long as they are interoperable
- Where does simplicity come from?
 - Outlaw non-determinacy!
 - Deterministic, Simple, parallel programming models
 - With Marc Snir, Vikram Adve, ..
 - Are there examples of such paradigms?
 - Multiphase shared Arrays : [LCPC '04]
 - Charisma++ : [LCR '04]

Shared memory or not

- Smart people on both sides:
 - Thesis, antithesis
- Clearly, needs a "synthesis"
- "Shared memory is easy to program" has
 - Only a grain of truth
 - But there exists that grain of truth
- We as a community, need to have this debate
 - Put some armor on, drink friendship potion, but debate the issue threadbare..
 - What do we mean by SAS model and what we like and dislike about it

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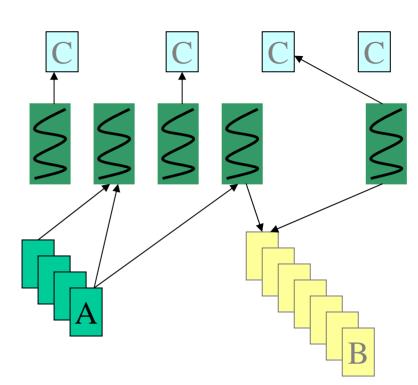
Multiphase Shared Arrays

- Observations:
 - General shared address space abstraction is complex
 - Certain special cases are simple, and cover most uses
- Each array is in one mode at a time
 - But its mode may change from phase to phase
- Modes
 - Write-once
 - Read-only
 - Accumulate
 - Owner-computes

• All workers **sync**, at end of each phase

MSA:

- In the simple model:
- A program consists of
 - A collection of Charm threads, and
 - Multiple collections of data-arrays
 - Partitioned into pages (user-specified)
- Execution begins in a "main"
 - Then all threads are fired in parallel
- More complex model
 - Multiple collections of threads
 - ...



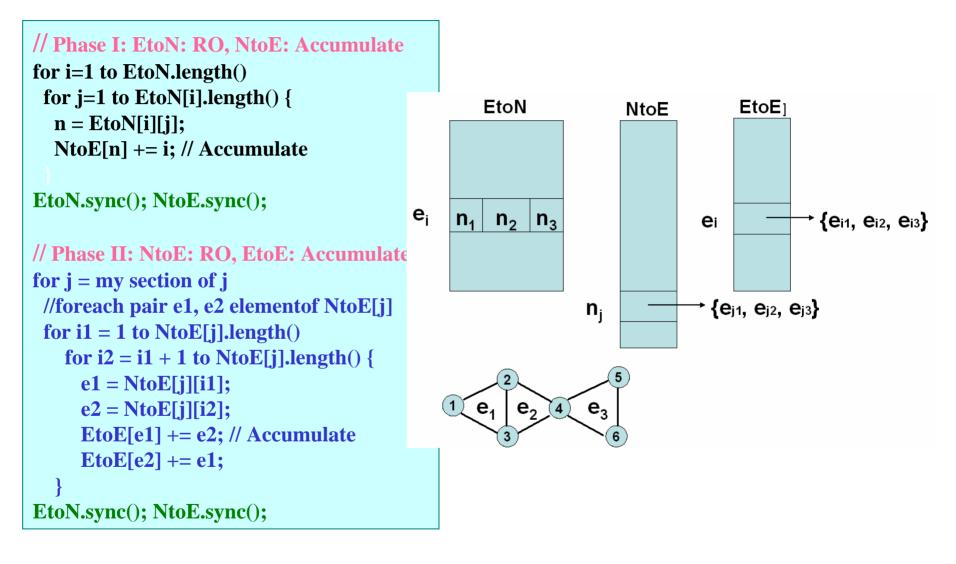
MSA: Plimpton MD

```
for timestep = 0 to Tmax {
  // Phase I : Force Computation: for a section of the interaction matrix
  for i = i_start to i_end
    for j = j start to j end
      if (nbrlist[i][j]) { // nbrlist enters ReadOnly mode
        force = calculateForce(coords[i], atominfo[i], coords[j], atominfo[j]);
        forces[i] += force; // Accumulate mode
        forces[i] += -force;
 nbrlist.sync(); forces.sync(); coords.sync(); atominfo.sync();
  for k = myAtomsbegin to myAtomsEnd // Phase II : Integration
     coords[k] = integrate(atominfo[k], forces[k]); // WriteOnly mode
  coords.sync(); atominfo.sync(); forces.sync();
  if (timestep %8 == 0) { // Phase III: update neighbor list every 8 steps
     for i = i start to i end
        for j = j start to j end
         nbrList[i][j] = distance( coords[i],coords[j]) < CUTOFF;</pre>
   nbrList.sync(); coords.sync();
}
```

Extensions

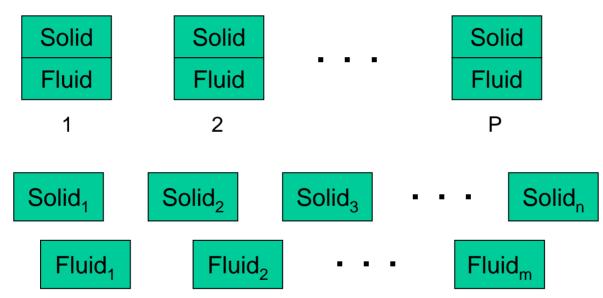
- Need check for each access: is the page here?
 - Pre-fetching, and known-local accesses
- A Twist on ACCUMULATE
 - Each array element can be a set
 - Set Union operation is a valid accumulate operation.
 - Example:
 - Appending a list of (x,y) points

MSA: Graph Partition



Charisma: Motivation

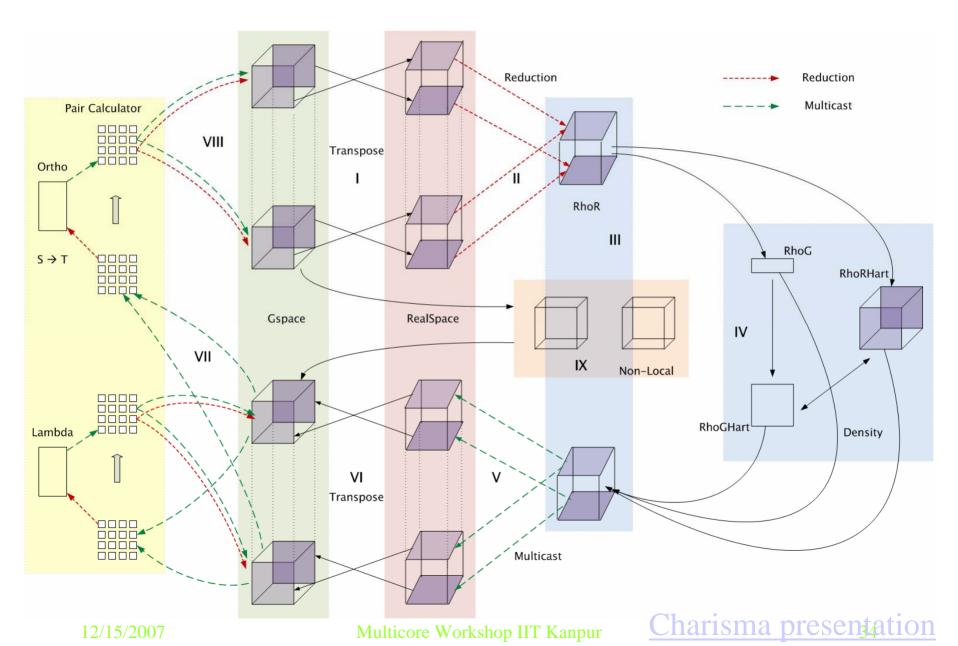
• Rocket simulation example under traditional MPI vs. Charm++/AMPI framework



- Benefit: load balance, communication optimizations, modularity
- Problem: flow of control buried in asynchronous method invocations

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Motivation: Car-Parrinello Ab Initio Molecular Dynamics (CPMD)



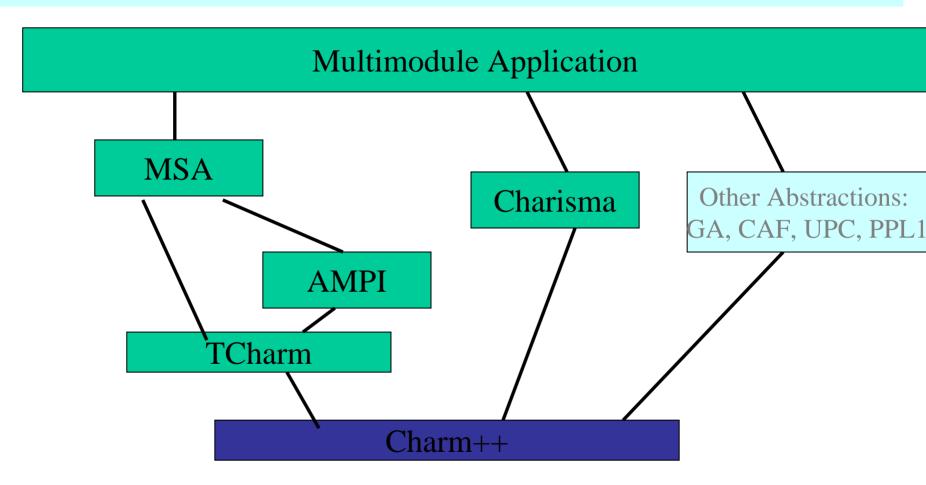
Charisma++ example (Simple)

```
Jacobi 1D
    begin
     forall i in J
      <lb[i],rb[i]> := J[i].init();
     end-forall
     while (e > threshold)
      forall i in J
        <+e, lb[i], rb[i]> := J[i].compute(rb[i-1],lb[i+1]);
      end-forall
     end-while
    end
```

Mol. Dynamics with Spatial Decomposition

```
foreach i,j,k in cells
           <atoms[i,j,k]>:= cells[i,j,k].produceAtoms();
end-foreach
for iter := 0 to MAX_ITER
  foreach i1,j1,k1,i2,j2,k2 in cellpairs
    <+forces[i1,j1,k1]> :=
        cellpairs[i1,j1,k1,i2,j2,k2].computeCoulombForces(
                                      atoms[i1,j1,k1],atoms[i2,j2,k2]);
  end-foreach
  foreach ... for bonded forces.. Uses atoms and add to forces
  foreach i,j,k in cells
         <atoms[i,j,k]> := cells[i,j,k].integrate(forces[i,j,k]);
  end-foreach
end-for
```

A set of "incomplete" but elegant/simple languages, backed by a low-level complete one



Lets play together

- Multiple programming models need to be investigated
 - "Survival of the fittest" doesn't lead to a single species, it leads to an eco-system.
- Different ones may be good for different algorithms/domains/...
- Allow them to interoperate in a multi-paradigm environment

Summary

- It is necessary to raise the level of abstraction
 - Foundation: adaptive runtime system, based on migratable objects
 - Automate resource management
 - Composibility
 - Interoperability
 - Design new Models that avoid data races, and promote locality
 - Incorporate good aspects of shared memory model

More info on my group's work: http://charm.cs.uiuc.edu