# Spatial Role Labeling

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# Introduction

Spatial role labeling is the task of automatic labeling of words and phrases in a sentence with a set of spatial roles such as trajector, landmark, spatial indicator, distance, direction etc

#### Example

John(Trajector) is sitting on(Spatial Indicator) the ground(Landmark)

The vase(Trajector1) is on(Spacial Indicator1) the ground(Lanmark1,Trajector2) on(Spatial Indicator2) your left(Landmark2)

Spatial indicators: Signals a spatial relation between objects (trajectors and landmarks) of a spatial scene.

Trajector : Entities like a person, object or event whose location is described.

Landmark: The reference entity in relation to which the location or trajectory of the trajectors motion is specified.

## Dataset

The data we got from the organizers of SemEval'12 in XML format. It consists of around 600 labeled sentences

#### Examples

About 20 kids in traditional clothing and hats waiting on stairs <TRAJECTOR id="tw2"> Kids</TRAJECTOR> <LANDMARK id="lw10"> Stairs</LANDMARK> <SPATIAL\_INDICATOR id="sw9">on </SPATIAL\_INDICATOR>

# Work Flow



# Stanford Dependency Parsing

Input :

Bills | NNS on | IN ports | NNS and | CC immigration | NN were | VBD submitted | VBN by | IN Senator | NNP Brownback | NNP , | , Republican | NNP of | IN Kansas | NNP

Output



nsubjpass(submitted, Bills) auxpass(submitted, were) agent(submitted, Brownback) nn(Brownback, Senator) appos(Brownback, Republican) prep\_of(Republican, Kansas) prep\_on(Bills, ports) conj\_and(ports, immigration) prep\_on(Bills, immigration)

Image Src : http://nlp.stanford.edu/software/stanford-dependencies.shtml

### Naïve Bayes

Given  $x_{1..n}$  as n words of a sentence and  $y_{1..n}$  as n labels. Then in Naïve Bayes algorithm

$$P(x,y) = P(y) \prod_{i=1}^{n} P(x_i | y_i)$$

In Naïve Bayes algorithm we consider conditional independence among different words of a sentence

$$(P(x_i | y_i, x_j) = P(x_i | y_i))$$

#### Naïve Bayes Training

#### Input Format

[[Trajector,Trajector.Lemma,Trajector.POS], [Landmark, Landmark.Lemma,Landmark.POS],[Preposition,Preposition.Lemma,Prepositi on.POS], Spatial sense]] – TAG (1 means is a spatial indicator)

The spatial sense is calculated using the tpp dataset(which a large corpus of preposition along with it senses

#### Example

About 20 kids in traditional clothing and hats waiting on stairs [[kids,kid,NNS], [clothing,clothing,NN], [in,IN,prep],0.13]] - 0 [[waiting,waiting,VBG], [stairs,stair,NNS], [on,IN,prep],0.25]] – 1

## Results

Spatial Role	Accuracy
Spatial Indicator	83%
Trajector	76%
LandMark	79%

These Results are obtained on taking 480 sentences for training and 120 dataset for testing

## Future Work

- Append Word to vector as an additional feature in the feature dataset
- Using learning approaches like Conditional Random Field which is basically maximization of conditional probability of labels given all the set of observations

## Acknowledgement

- TPP Data set : (Semevall 2007 Task of word sense disambiguation for preposition)
- Semeval 2012 Dataset : <u>http://www.cs.york.ac.uk/semeval-</u> 2012/task3/
- Code Modified: <u>https://code.google.com/p/pln-pmt-pract/</u>
- Paper Referred : Parisa Kordjamshidi, Martijn van Otterlo, and Marie-Francie Moens. Spatial role labeling: Towards extraction of spatial relations from natural language. ACM Transactions on Speech and Language Processing, Nov. 2011.
- Python NLTK Library (nltk.pos\_tag(), nltk.lemma())